

AIR FORCE

AIRBORNE PERFORMANCE MEASUREMENT SYSTEM DESIGN: C-5 AIRCRAFT

By

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SUMMARY

The objectives were to define the requirements for an aircrew performance measurement system (PMS) for the C-5 aircraft and, based on these requirements, to develop a system design specification for an airborne PMS that would gather data from the aircraft and generate objective measures of aircrew performance.

Commencing in 1976, a research and development (R&D) effort defined the requirements for a PMS for C-5 aircrew members. The resulting PMS was installed on a C-5A flight simulator to provide the instructor with real-time and post-mission feedback of student performance, as well as to record proficiency assessment data for future analysis. Next, an airborne PMS capability was to be developed so that equivalent measures of crew performance could be generated in both the simulator and the aircraft. This R&D was conducted in three phases. Phase I identified and defined the required functional capabilities of an airborne PMS. Phase II analyzed the systems of the C-5 to identify available signal sources for use by the PMS and developed a series of design approaches for an airborne PMS. Phase III produced a system design specification for the selected airborne PMS system.

Interviews and discussions were conducted to determine training and R&D needs, and the results were used to define an airborne nominal mission. mission was compared to an equivalent simulator PMS mission in order to define the airplane signal requirements; however, not enough signal information could be extracted from the C-5 to fully support an airborne PMS equivalent to a Enough data could be obtained to simulator PMS. provide equivalent measurement in approach and landing crew performance; therefore, alternative design approach resulted in a detailed specification that conceptualized airborne PMS as composed of two systems interfaced to each other by a recording medium. The C-5 airborne recording system is composed of a microprocessor-based controller which extracts data from three airplane systems and records the data on magnetic tape. The ground-based processing system employs the simulator PMS hardware plus a magnetic tape unit and It will process recorded data from the airplane and modified software. produce outputs equivalent to the simulator PMS.

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It is concluded that development of a fully equivalent simulator/airborne PMS for the C-5 is not feasible due to the requirement for a large number of signals and the need for extensive modifications to obtain these. It is recommended that PMS requirements be considered as an integral part of the initial aircraft design to avoid retrofit problems experienced in this C-5 PMS design attempt.

PREFACE

This research represents a portion of the program of the Air Force Human Resources Laboratory Technical Planning Objective, the thrust of which is air combat tactics training. The general objective of this thrust is to identify and demonstrate cost-effective training strategies and training equipment for use in developing and maintaining the combat effectiveness of Air Force aircrew members. The specific problem addressed by this effort was the lack of an objective means of assessing crew performance in the aircraft and the relation of such measures to performance in the simulator. The purpose of the study was to design a system whereby objective performance data could be collected in the C-5 aircraft. The effort is part of Project 2359, Pilot Performance Measurement Systems, and represents a follow-on to the development of a measurement system for the C-5 flight simulator. The work was accomplished by Logicon, Inc., San Diego, California, under contract F-33615-83-C-0025. Mr. Charles Schmitt was the Principal Investigator for Logicon, Inc. Dr. Wayne L. Waag was the contract monitor for the Air Force Human Resources Laboratory.

The conduct of this effort was made possible by the outstanding support of personnel from the Military Airlift Command. Major James Stephenson served as the principal point of contact at MAC Headquarters at Scott AFB, Illinois. Lt Col Ruud Hartog, 443 MAW/DOS was the principal point of contact from the training wing at Altus AFB, Oklahoma. SSgt Duane Brown served as the focal point for those aspects of the effort concerning the flight engineer crew position. Their assistance throughout all phases of the effort was considered invaluable. And finally, special thanks are extended to all squadron personnel at Altus AFB whose professional attitudes and expertise made this work possible.

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SECTION I

INTRODUCTION

Background

The advance of technology in the use of simulators for flight training has been substantial since the first design of simulators. Today, flight training simulators are highly complex devices capable of total aircrew training of almost all flight tasks. The increased procurement and operating costs of both aircraft and simulators have resulted in an awareness of the need to quantify the effectiveness of training techniques in order to achieve the most cost-effective overall training approach.

Performance measurement techniques are an essential component of aircrew training programs. Specifically, they must be used to measure objectively the progress of students through the training and to determine the effects of training program modification.

In late 1973, the Air Force Human Resources Laboratory (AFHRL) initiated a consulting dialogue with the Military Airlift Command (MAC). In an attempt to obtain further assistance, MAC initiated a Request for Personnel Research (RPR) in which one of the objectives concerned the application of training effectiveness measurement to the evaluation of their training programs. Although the initial RPR was not approved, these objectives were included in the Air Force Master Simulation Plan and the dialogue between AFHRL and MAC continued. In May 1976, MAC initiated another RPR (76-20), entitled "Aircrew Performance Measurement System," which was subsequently validated.

The objectives of this RPR were:

- To identify objectively the mission task requirements for MAC aircrew members through an analysis of training syllabuses, STAN/EVAL performance criteria, and flying training records when appropriate.
- 2. To describe current and planned flight simulator and aircraft capabilities in terms of their use in generating mission performance measurement for MAC aircrew members.
- 3. To develop and evaluate an objective/quantitative measurement system for MAC aircrews based on the mission task requirements and the capabilities of command flight simulation systems as well as the aircraft.

A joint effort by AFHRL and MAC was initiated with the goal of developing a prototype system for the C-5 aircraft.

In July 1976, the Air Force awarded a three-phase research and development (R&D) contract entitled "Definition of Requirements for a Performance Measurement System for C-5 Aircrew Members." The general objective of the effort was to define requirements for a valid, reliable, objective/quantitative performance measurement system for members of the C-5 aircrew, utilizing the existing C-5 simulator. The R&D was subsequently extended to determine the feasibility of expanding the performance measurement beyond the simulator to include the C-5 aircraft. The complete results of the research effort were published as an AFHRL technical report (Swink et al., 1978).

Based on the functional requirements described by Swink et al. (1978), a contract was awarded in 1978 for the development, fabrication, and integration of a Performance Measurement System (PMS) for the C-5A flight simulator. The PMS developed is currently operational with a C-5A flight simulator located at Altus AFB. The simulator PMS provides for real-time aircrew performance measurement in the areas of checklist/procedure execution, navigational profile adherence, and parameter monitoring. In addition, the PMS provides for the automatic insertion of simulator malfunctions. The PMS provides the instructor with real-time and post-mission feedback of student performance. It also provides for the recording of proficiency assessment data for future retrieval and statistical analysis.

Study Objective and Tasks

The complete study of aircrew performance measurement must include both the simulator and the airplane environment. Of critical importance is the relationship of measured performance in the simulator to measured performance in the aircraft. Ideally, what is required is an intregrated simulator/airborne performance measurement system which enables the generation of equivalent indices of aircrew proficiency in both environments. The objectives of this effort were to define the requirements for an airborne measurement system and to develop a design specification based on the requirements.

The work was conducted in three phases having the following objectives:

- 1. Phase I To identify and define the required functional capabilities of the airborne PMS.
- 2. Phase II To analyze the availability of required airborne data signals and to define alternate approaches to provide an airborne recording capability and a ground-based processing system.
- 3. Phase III To develop a specification for an airborne performance measurement system including the airborne recording system and the ground-based processing system.

SECTION II

PHASE I - REQUIREMENTS

The objective of Phase I was to analyze the requirements for performance measurement of C-5 crew members during the period of flight training. The training period considered was the flight training section of the copilot and flight engineer initial qualification courses. The goal of this phase was to define the set of required functional capabilities for an airborne performance measurement system which would support the objective evaluation of aircrew proficiency. An additional task of this phase was an analysis of the C-5 recording capabilities to determine sources of crew performance data. The data sources for this analysis consisted of operational and training documentation, interviews with instructors and evaluators, and discussions with research personnel.

Research and Development Needs

The Air Force Human Resources Laboratory (AFHRL) has sponsored C-5 PMS study and development efforts since the commencement of the program in 1976. While a side goal of the airborne PMS is to enhance C-5 crew training, the primary benefit is to obtain crew performance data for AFHRL use. The data collected will be used by AFHRL and other agencies to assess the effectiveness of airborne and simulator training and the transferability of training from the simulator to the aircraft. In addition, these data may be utilized to predict or test the effects of training program modifications.

The AFHRL data requirements fall into two categories: raw data and processed data. Raw data can be defined as data extracted and recorded exactly as it is generated by airplane systems. This same type of data has been targeted to be recorded by the simulator PMS. Two examples of raw data are parameters describing the state position of the aircraft (e.g., altitude, airspeed, position) and parameters that monitor control activity (e.g., yoke movement, throttle position). The recorded raw data could be used in a comparison of equivalent data from the simulator and the aircraft, such as a comparison of throttle movements on final approach.

Processed data are defined as performance data which have been extracted, processed according to predefined algorithms, and recorded as summary measures of aircrew performance. A primary goal of the C-5 performance measurement system is to produce equivalent measures of aircrew performance in both the simulator and flight environments. Therefore, the same scoring procedures should be used. This implies that the same types of measures that are generated for checklist/procedures, navigational profiles, and monitorable parameters by the simulator PMS should be generated by the airborne PMS.

The intent is thus to provide a set of processed data and measures for the establishment of statistical relationships between performance measures collected in the simulator and the aircraft.

There are currently two primary users of the raw and processed data produced by the performance measurement system. The Operations Training Division of AFHRL is concerned primarily with the establishment of relationships between simulator-based and aircraft-based performance measures. The Manpower and Personnel Division of AFHRL is interested in using the measures of crew performance as criteria in the validation of new selection procedures.

Training Needs

An investigation was conducted to determine Altus AFB training needs with respect to potential airborne PMS applications. The investigation was conducted through an examination of operational and training documentation, and through interviews with instructor pilots, instructor flight engineers, and flight examiners. The feedback provided to instructors by the simulator PMS was used as a basis for potential feedback from an airborne PMS.

The basis for the Altus training needs investigation was the Copilot Initial Qualification Course and the Flight Engineer Initial Qualification Course. The initial qualification courses consist of a sequence of several types of instructional methods. These include the use of classroom lectures, the Cockpit Familiarization Trainer (CFT), the Cockpit Procedural Trainer (CPT), the C-5 flight simulator and C-5 flights. The C-5 flight simulator training environment was addressed by the simulator PMS.

The flying phase of initial qualification training is devoted primarily to normal flying procedures. Emphasis is placed on defined normal procedures, flight safety, aircrew coordination, and aircrew standardization. Students normally receive four training flights followed by a flight evaluation. Each flight consists of pre-mission briefing, flight planning, a 4-hour flight, and post-mission activities including a mission debriefing.

Interviews with instructors were conducted to determine areas of this flying phase where an airborne PMS could enhance training needs. It was determined that the majority of debriefing or correction of errors was accomplished immediately when the error occurred. The ground mission debriefing highlights only the more serious errors or discusses alternate techniques. The instructors did not feel that a post-mission summary of checklist execution or parameter value maintenance would be useful. Most instructor pilots, however, expressed an interest in a graphic representation of the approaches flown. The instructors stressed that, to be useful, the PMS data must be available for the post-mission debriefing.

Additional Needs

In addition to the R&D and training requirements, several other uses of an airborne PMS were identified. Statistical data gathered over the running of several training missions would be useful to both personnel at MAC headquarters and to course development personnel. The data can

identify course areas which are weak and require more training, as well as areas for which there may be too much training. An airborne PMS would provide the capability to measure pilot performance in the aircraft as it is done in the simulator. Such measurements would allow analysis of the transfer of training from the simulator to the airplane. It would provide a vehicle to determine those tasks which can be entirely simulator trained and not required in airborne training.

Definition of Airborne Nominal Mission

The R&D and training needs described above established the user requirements of the airborne PMS. The next step was to determine the measurement requirements of the airborne system. The method employed to determine these measurement requirements was to construct an airborne nominal mission. The airborne nominal mission consists of the sequence of required tasks and crew activities typically found on the final evaluation flight of the Copilot Initial Qualification Course. It is constructed utilizing the syntax and format defined for the mission generation program which is employed by the simulator performance measurement system. The original intent was to design an airborne nominal mission which was equivalent to the already defined simulator nominal mission. Comparison of the resulting missions would then allow evaluation of the equivalence of the missions and definition of the differences between the missions. It was soon recognized, however, that the simulator PMS nominal mission was not compatible with the approach to airborne training.

The simulator PMS nominal mission is defined with takeoff from one airfield, flight cross country, and a landing at another airfield. Airborne training is conducted at a single airfield utilizing a series of touch-and-go landings. The study approach was modified and an airborne PMS nominal mission was defined in accordance with airborne flight training requirements. At the same time a simulator nominal mission was defined which is both "equivalent" to the airborne mission and also corresponds to the final simulator training session prior to flight training. The simulator version includes malfunctions, but the scoring of comparable normal checklists should not be affected. This approach provides simulator training and flight training with compatible missions and achieves the objectives of the airborne PMS to measure equivalent types of tasks and crew activities. Appendix A is a listing of the defined airborne nominal mission illustrating the monitored activities. Appendix B is a listing of the defined simulator nominal mission which corresponds to the airborne nominal mission.

The two nominal missions, simulator and airborne, are similar in design. The task and crew activities in both are based on respective Altus AFB training requirements and AFHRL R&D requirements. They both are flown from Altus AFB and use runway 35 as the primary runway; they commence with the aircraft on the ground. In each case, all the normal checklists, with the exception of After Takeoff Climb, Cruise, and Descent, are monitored. The Before Landing checklist is monitored before each landing. The standard list of parameters is monitored for both missions. Both missions contain a like sequence of navigational profiles to be used for touch-and-go landings. Both missions terminate with a full-stop landing.

Two main areas of difference exist between the simulator and airborne nominal missions. The first, as mentioned earlier, is in the area of malfunctions. The airborne nominal mission contains no planned malfunctions. An exception to this is the loss of one engine, which is simulated by placing the throttle to idle. All other emergencies are only talked through. In the simulator mission actual malfunctions are inserted and the associated checklists are monitored and assessed.

Another area of mission difference is the availability of mission setup data. In the simulator mission, a series of values associated with aircraft configuration, told card worksheet, and weather are specified in advance for PMS use. These data are used in mission initialization and in the monitoring of some checklists and procedures. These data can be held constant for each simulator mission but vary for each real airborne mission flown. Therefore, such setup data cannot be specified during mission definition of the airborne mission and must be provided after the mission is flown. Along this same line, all simulator nominal missions use runway 35, whereas airborne nominal missions may use either runway 35 or runway 17 as dictated by daily weather conditions. When runway 17 is used, a direct comparison cannot be made with the simulator mission in regard to navigational profiles without changing the simulator mission profile. Checklist and parameter comparisons would still be valid.

Another area should also be considered when the airborne and simulator nominal missions as defined are compared. Although both missions contain the same types of navigational profiles and checklists, the order of execution and the number of times executed are dependent on several factors. Therefore, it is unlikely that summary level scores (mission, all checklists, pilot total, etc.) will be comparable. At an individual task level (e.g., Before Landing Checklist), however, the scores are comparable.

Required Functional Capabilities

The initial activities of Phase I of the effort were directed toward definition of the needs, both training and R&D, of an airborne performance measurement system. An analysis of these R&D and training needs of AFHRL and Altus AFB, respectively, combined with an analysis of the airborne nominal mission served as the basis for the definition of the required functional capabilities of the airborne performance measurement system. The analysis of the functional capabilities considered the following areas:

(a) scope, in terms of flight tasks and parameters, (b) data storage, (c) data display, retrieval, and analysis, (d) compatibility with simulator PMS, and (e) instructor data entry.

Scope of Airborne Measurement Capability. The scope of the airborne performance measurement capability can be defined in terms of aircrew tasks identified in the airborne nominal mission, as defined in Appendix A, and the airplane data associated with these tasks. The airborne mission was defined to be compatible with a corresponding simulator mission so that equivalent measurement indices could be obtained. The mission is designed to quantify operational activities required of the various crew members while performing their inflight duties during a typical training flight.

をあるというというとは、これをはなるのである。これできるできないできないできない。 できることできることが、これできるとのできるとのできるというできるというできる。 The tasks defined are delineated under the phases associated with sircraft operation for flight training. These phases are oriented toward preflight, takeoff, approach, and landing. They are described in terms of exactly two distinct crew positions: copilot and flight engineer. The aircrew tasks that are to be measured fall into three classes under the PMS concept: (a) normal checklists/procedures, (b) navigational prefiles, and (c) monitorable parameters.

The airborne PMS nominal mission will monitor a total of 32 checklists and procedures as listed below. The flight engineer interior checklist is divided into eight parts for PMS purposes due to its length and complexity.

Pilot/Copilat

Before Starting Engines Starting Engines Before Taxi Taxi Before Takeoff Lineup Takeoff Throttle Setting Approach Before Landing Landing After Landing Engine Shutdown Before Leaving Airplane

Flight Engineer

Before Interior
Interior - Steps 1 to 15
Interior - Steps 16 to 30
Interior - Steps 31 to 37
Interior - Steps 38 to 60
Interior - Steps 61 to 66
Interior - Steps 67 to 73
Interior - Steps 74 to 80
Interior - Steps 81 to 105
Before Starting Engines
Starting Engines
Before Taxi
Before Takeoff
Standard Fuel Management
Approach
Before Landing
After Landing
Engine Shutdown
Before Leaving Airplane

Three types of navigational profiles are defined in the nominal mission to monitor the ability of the crew to adhere to predefined approach profiles:

- 1. Instrument Departure
- 2. Initial Approach and Non-Precision Final
- 3. Instrument Landing System Precision Final

The airborne nominal mission is defined to monitor the standard list of monitorable parameters. These measure the ability of the crew to maintain airplane systems within predefined limits during various phases or envelopes of operation. The standard list of monitorable parameters is as follows:

25 and 75 Liter Oxygen Quantity AC Frequency Meter AC Voltmeter Airspeed Angle of Attack Cabin Flight Altitude

Cabin Pressure Difference CSD 1, 2, 3, 4, 0il Temperature DC Voltmeter Engine 1, 2, 3, 4 EPR Engine 1, 2, 3, 4 Fuel Flow Engine 1, 2, 3, 4 9il Pressure Engine 1, 2, 3, 4 Cil Temperature Engine 1, 2, 1, 4 M2 RPM Engine 1, 2, 3, 4 TIL Flap Position Left, Right Manifold Tissarre Landing Gear Lever Left, Right APU Exhaust Gas Temperature Landing Gear Position Mach Magnetic Heading Pitch Rol1 Yaw System 1, 2, 3, 4 Hydraulic Pressure

Each of the tasks listed above (checklist/procedures, navigational profiles, monitorable parameters) was analyzed to determine the C-5 data required to measure completely the performance of the aircrew. Since each of these tasks was previously defined for the simulator PMS, their definitions were used as the basis for the analysis. The data fell into two classes. The first class is the data required to perform the actual measurement. The second class is data used to define conditions to determine when to start and stop the measurement of each task. A summary of the results of this analysis follows.

To monitor the defined checklists requires that 411 distinct signal values be extracted from the airplane. Monitoring of navigational profiles requires 40 values, and 121 values are required for monitorable parameters. There is some overlap among the three classes of tasks, so that 494 total signal values must be extracted from the airplane to monitor completely the airborne nominal mission as defined in Appendix A.

The signals required for airborne monitoring are presented in Appendices D through H. These appendices contain:

Appendix D - Code reference for Appendix E through Appendix H
Appendix E - Signals required for airborne monitoring
Appendix F - Signals required for individual checklists
Appendix G - Signals required for individual parameters
Appendix H - Signals required for navigational pufiles

Data Storage Requirements. The amount of storage required to maintain the data extracted from the simulator is a function of several factors. The requirements for the ground-based processing for the airborne PMS are a direct result of the airborne recording requirements; therefore, the storage analysis was done for the airborne recording system alone.

The basic cycle rate required for data extraction is assumed to be 0.8 second. This corresponds to the current simulator PMS. A typical flight training mission covers a 4-hour period. Due to the nature of the training involving many takeoffs and approaches, signal values will change with a high frequency. Some form of filtering or trending algorithm must be applied to the data to reduce the amount of data ultimately recorded.

Table 1 depicts the amount of data storage required for a typical mission. The actual amount of recorded data is dependent on two factors: the percentage of total signals that changes every recording interval and the number of bytes required to record each item. For example, if an average of three percent of the signals changed every recording interval and five bytes are required to record each item, then 1,333,800 bytes of data storage would be required for a 4-hour mission.

Table 1. AIRBORNE NOMINAL MISSION DATA STORAGE REQUIREMENTS

% items changing	Number of items	Number of items		Number of by	tes per item	ı
in .8 sec			3	44	55	6
1	5	88,920	266,760	355,680	444,600	533,520
2	10	177,840	533,520	711,360	889,200	1,067,040
3	15	266,760	800,280	1,067,040	1,333,800	1,600,560
4	20	355,630	1,067,040	1,422,720	1,778,400	2,134,080
5	25	444,600	1,333,800	1,778,400	2,223,000	2,667,600
10	49	889,200	2,667,600	3,556,800	4,446,000	5,335,200
25	124	2,223,000	6,669,000	8,892,000	11,115,000	13,338,000
50	247	4,446,000	13,338,000	17,784,000	22,230,000	26,676,000
75	371	6,669,000	20,007,000	26,676,000	33,345,000	40,014,000
100	494	8,892,000	26,676,000	35,568,000	44,460,000	53,352,000

Data Display, Retrieval, and Analysis Requirements. The ultimate goal of the airborne PMS is to produce objective measures or performance which can be compared against such measures from other airborne missions or against equivalent measures from the simulator PMS. Creating such equivalent measures is easiest if, to the greatest extent possible, both airborne and simulator PMSs monitor, score, and analyze crew performance in the same fashion. The following discussion traces the path of monitored crew data through the simulator performance measurement system.

The simulator PMS monitors the aircrew performance against procedures and standards established for the mission by the mission designers. During a mission PMS logs, to a disk file, data on checklist step execution, average aircraft parameter errors, and navigational profile adherence. At mission's end a debriefing program then serves two purposes. First, it scores achieved performance recorded in the mission log against predefined standards and

scoring criteria. It then produces a printout containing computed scores and summaries. Second, in addition, the program records all scoring parameters in a Proficiency Assessment Records (PAR) disk file. The printout becomes both a hardcopy debriefing device for instructors and a conveniently organized reference for subsequent scoring data analysis.

The simulator PMS also provides for the retrieval of an arbitrary set of scoring data from any union of PAR files into a Retrieved Data File (RDF). PMS further provides statistical analysis of these retrieved data. At present the analysis is limited to descriptive statistics. The analysis program also reorganizes summary data into a format suitable for shipment to AFHRL for further analysis.

At minimum, the airborne PMS should produce assessment data in standard PAR file format. Such data can simply be processed directly by the existing PMS retrieval and analysis programs. Comparison of simulator and airborne performance would then be a matter of merely combining the proper files for analysis.

Even more desirable from a hardware/software compatibility viewpoint would be an airborne PMS whose monitoring output was in PMS log-file format. The PMS debriefing program could then process the log, producing both standard PAR files and some form of debriefing report. Again, such a report would be useful both to instructors and to mission analysts, although the timeliness of such a report for mission debriefing is problematical.

Regarding airborne display requirements, the airborne PMS will generate no real-time displays, either of performance feedback or geographic track history. However, ground-based post-mission processing could produce hardcopy graphics of the navigational profiles flown in the mission. Such graphics would momentarily appear on a CRT display for transfer to the hardcopy medium.

Compatibility Requirements with Simulator PMS. A critical consideration in designing an airborne PMS to fulfill the goals of the overall program is the compatibility of the airborne and simulator PMS designs. In order to provide the means to analyze equivalent measures from simulator and airborne missions, it is advantageous for the two systems to have common data paths in their processing as early as possible. The previous sections recommended that this point of commonality be the mission log file. Commonality is also enhanced if the system which processes the airborne recorded data utilizes the same algorithms and programs developed for the simulator PMS.

Instructor Data Entry Requirements. The simulator PMS provides two methods to start the monitoring of performance tasks: automatic and manual. The automatic method starts monitoring a task when mission-specified start conditions have been satisfied. These start conditions can include completion "links" from checklists, execution of a checklist step, geographical position, etc. The manual method allows the instructor to start a task (checklist/procedure, navigational profile, monitorable parameter) from a keyboard attached to the PMS.

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The airborne PMS will require similar indications to the ground-based processing system as to when to start monitoring a task. If enough signals could be acquired from the airplane, then automatic monitoring start of checklists/procedures and monitorable parameters would be possible. Navigational profile start is less easy to identify, as all profiles in the airborne mission basically start in the same general location and can appear in random order. This is also true for the equivalent simulator nominal mission, unless the instructor/mission designer predetermines the exact sequence of profiles.

Therefore, an on-board entry device is required for instructor entry of annotation of the start of certain events. As a minimum, this must include the designation of the type of navigational profile being flown and when to start the monitoring. This device could also be used to start manually monitoring checklists and parameter envelopes at the command of the instructor.

The on-board entry device must be as simple to operate as possible. This is necessary so as not to add to the workload nor distract the instructor from the safe operation of the aircraft. The output of the on-board entry device must be recorded on the PMS recording device for use by the ground-based processing system.

Recording Capability of C-5. The subsystems of the C-5 aircraft were analyzed to determine existing capabilities to provide recorded data for use by the airborne PMS system. The only system which already records aircraft data in a reasonable form for extraction of data is the Malfunction Detection, Analysis and Recording System (MADARS). The potential use of the MADARS is complicated by the planned replacement of this equipment in the near future.

The MADARS is a computerized data collection, processing, and recording system. The express purpose of MADARS is to assist the flight engineer and ground crews in checking airplane line replaceable units and subsystems for degradation or failure. The data collected by MADARS is also used to establish long-term failure trends to improve spares logistic support, as well as provide a useful tool for maintenance troubleshooting.

The data collection part of MADARS has 22 signal amplifier units located throughout the C-5A aircraft. Each amplifier has the capacity for 29 analog inputs and upon command, it selects one of 29 parallel analog input signals and transmits it to a central multiplexer. The central multiplexer controls the multiplexing of the signal amplifiers and digitizes the analog signals for computer operation.

The data collected by MADARS from the signal amplifiers are used in two ways. The MADARS computer programs analyze the data collected to determine the status of airplane systems. When a fault is detected, the flight engineer is notified and/or a fault code entry is made on the Maintenance Data Recorder (MDR). In addition, the MADARS computer performs a trend analysis of selected data values.

In the trend analysis, data are recorded only when the signal value changes by more than a predefined variance from an established baseline. When the signal values go out of the defined bounds, the signal value is recorded on the magnetic tape and established in the computer as the new baseline. The allowable variance for each signal is pre-assigned and is based on the usage of the recorded values. As an example of this trending operation, assume a mach number of .600 with an allowable variance of ± .010. A change in value of the function will not be recorded until it goes outside the .59 to .61 boundary range. If the value jumps to .612, then this value is recorded on the magnetic tape and established in the computer as the new base. The computer now uses .602 and .622 as the new boundary limits. This technique allows many functions to be monitored with a limited amount of recording speed and tape storage. Since the signals are all monitored at least once per second, the trending operation produces a representative monitoring of all functions.

An analysis was performed on the current MADARS to determine what signals are currently recorded or could be recorded with program modifications to support to airborne PMS data extraction requirements. Approximately 72 of the 494 signals required for the airborne PMS can be made available.

The potential MADARS signals are:

- EPR

Air Conditioning Switch Engine 4 - A/I Switch ALDCS Switch - Bleed Air Switch Altitude - EPR Cargo Switch - Fuel Flow Co-Pilot Altitude - Fuel Heater Switch Engine 1 - A/I Switch - N1 RPM - Bleed Air Switch - N2 RPM - EPR - Oil Pressure - Oil Temperature - Fuel Flow - Fuel Heater Switch - N1 RPM Flap Position Indicator - N2 RPM Flight Station Switch - Oil Pressure Floor Heat Switch - Oil Temperature Generator Volts and Frequency Switch - TIT Ground Spoiler Handle Engine 2 - A/I Switch Left Flow Control Switch - Bleed Air Switch Left Manifold Pressure Landing Gear Lever - Fuel Flow Left APU EGT Indicator - Fuel Heater Switch Lateral Augmentation Switch - N1 RPM Mach - N2 RPM On-Ground Indicator - Oil Pressure Pilot Altitude - Oil Temperature Pitch Augmentation Switch - TIT Right Flow Control Switch Engine 3 - A/I Switch Right Manifold Pressure - Bleed Air Switch Right AFU EGT Indicator

Relief Crew Switch

- Fuel Flow - Fuel Heater Switch - N1 RPM

- Oil Pressure

~ Oil Temperature

- TIT

- N2 RPM

Throttle 1 Position
Throttle 2 Position
Throttle 3 Position
Throttle 4 Position
Total Fuel Quantity
Troop Compartment Switch
Vertical Accelerometer
Yaw Augmentation Switch

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Preliminary indications of the replacement MADARS show that it will have about the same capability. The majority of the missing signals are discrete switch positions required for checklist monitoring.

Other airplane systems have available some of the remaining required signals, but have no means of recording them for ground processing. The most notable of these systems are the Inertial Navigation System (INS) and the Flight Director Computer (FDC). Between them they provide another 14 signals required for the airborne PMS.

The potential FDC signals are:

Copilot Course Deviation Indicator
Copilot Course Deviation Indicator Warning
Copilot Glideslope Deviation Indicator
Copilot Glideslope Deviation Warning
Copilot Navigation Select
Pilot Course Deviation Indicator
Filot Course Deviation Indicator
Filot Glideslope Deviation Indicator
Pilot Glideslope Deviation Uarning
Pilot Glideslope Deviation Warning
Pilot Navigation Select
TACAN DME

The potential INS signals are:

Bank Latitude Longitude

As can be seen, the percentage of available airplane signals for optimal PMS processing is not large and is insufficient to fulfill the goals of the airborne PMS. The analysis of this deficiency and the definition of alternate design approaches were accomplished in Phase II of this effort. The results are described in the next section.

SECTION III

PHASE II - ALTERNATIVES

Phase I of the effort established the data requirements for the airborne performance measurement system that was equivalent in concept to the currently operational C-5A simulator performance measurement system. This phase involved an analysis of the required signal data base, an analysis of currently available signals, and an investigation of feasible alternate signal sources. These analyses resulted in the definition of alternative design approaches that could be taken to achieve an airborne PMS capability. This phase concluded with the presentation of an interim briefing for AFHRL and Altus AFB representatives. The interim briefing presented the findings of the needs analysis and the C-5 recording capability analysis. It also presented alternative design approaches for a C-5 airborne performance measurement system. Based on guidelines received at the conclusion of the briefing, the design approach presented in Section IV was formulated.

Parameter Analysis

The investigation of the recording capability of the C-5 resulted in a listing of 72 signals that could be obtained, either currently or with software modifications, from the MADARS. In addition, another 14 signals were designated as being potentially available from the INS and the FDC. These signals provide approximately 17 percent of the 494 signals required to do airborne performance measurement equivalent to the simulator performance measurement system.

The applicability of the available signals to PMS monitorable tasks is defined in Appendices F, G, and H. Very few tasks can obtain enough data to make a valid measurement. Table 2 summarizes the signal requirements for checklists, Table 3 for monitorable parameters, and Table 4 for navigational profiles. Table 5 presents a summary of total signal requirements.

The majority of the missing parameters are indications of discrete switch positions. These are used primarily in the monitoring of checklist execution. A small number of continuous or analog signals are also not readily obtainable. These signals are also used in checklist evaluation as well as the evaluation of navigational profiles and monitorable parameters.

An investigation was conducted of the C-5 airplane systems to attempt to find sources for the missing signals. The previously mentioned INS and FDC provide a wide range of signals related to the control of the aircraft during flight. Fourteen of these signals were identified as being useful for airborne performance measurement monitoring. The breakouts to these two systems to allow for data extraction are fairly simple in design. No other systems were discovered which could provide signals with simple airplane modifications.

Table 2. CHECKLIST SIGNAL REQUIREMENTS

UNAVAIL -ABLE	20	6	16	_	99	N	#	19	Ŋ	1 4	σ	শ্ৰ	6	17	N	817	11	28	35	57	8	6	23	31	27	ন	16	45	55	17	้ณ	-	363
AVAIL -ABLE	8	m	വ	-	8	•	7	-	0	ય	∞	0	m	'n	.	Ŋ	m	, 	16	7	g -		-		0	9	ഹ	8	₹	œ	15	0	48
OTHER SOURCES	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	o
MADAR	Ø	m	L		8	-	۲3	,	0	~	∞	0	m	'n	=	Ŋ	m	-	16	=	*	-			0	9	ഗ	~	7	œ	15	0	48
AIRPLANE RECUIRED	52	12	21	æ	68	m	9	50	Ŋ	1 43	17	#	12	19	်ဖ	53	17	29	57	61	49	10	77	32	27	10	21	24	69	25	17	-	411
INITIAL	0	0	0	0	-	0	-	0	0	0	0	0	,	0	0	0	0	0		0	0	0	0	0	0	-	0	-	0	0	_	0	5
MALFUNC -TIONS	က	0		0	8	0	0	0	0	9	0	0	0	≉	ω	0	0	0	0	0	0	0	0	0	0	0	၁	8	*	ω	-	0	32
NUMBER	55	72	22	ω	7.1	m	-	8	J.	6†	17	ন	13	23	17	53	†	59	25	61	617	10	77	32	27	11	21	20	73	33	19	-	844
CHECKLIST	FE - AFTER LANDING	P - AFTER LANDING	FE - APPROACH	P - APPROACH	FE - BEFORE INTERIOR	E - BEFORE LANDIN	- BEFORE LANDIN	E - BEFORE	- BEFORE LEAVING A	FE - BEFORE STARTING ENGINES	P - BEFORE STARTING ENGINES	- BEFORE TAKE O	0	FE - BEFORE TAXI	- BEFORE	FE - ENGINE SHUTDOWN	P - ENGINE SHUTDOWN	- INTERIOR (1- 1	FE - INTERIOR (16- 30)	- INTERIOR (31- 3	- INTERIOR (38- 6	- INTERIOR (61- 6	<u>~</u>	- INTERIOR (74-8	E - INTERIOR (81-10	P - LANDING	P - LINEUP	FE - STANDARD FUEL MANAGEMENT	- STARTING	P - STARTING ENGINES	- TAKEOFF	1	TOTAL
INDEX	C.03	•	C.10	c.11	۲.	C.13	۲.	•	C.20	C.21	C.22	C.23	C.24	C.25	c.26	C. 44	C.45	c.56	C.57	c.58	C.59	09.0	C.61	C.62	C.63	C.64	c.68	ດ.91	C.92	c.93	₽6°2	c.95	

Table 3. PARAMETER SIGNAL REQUIREMENTS

AND TOUR COMMENS OF THE PROPERTY OF THE PROPER

TNDEX	PARANETER	NUMBER	MALFUNC -TIONS	INITIAL /SETUP	AIRPLANE RECUIRED	MAUAR	OTHER SOURCES	AVAIL -ABLE	UNAVAIL -ABLE
\$									
P.01	25 LITER OXYGEN QUANTITY IND	D 2	0	0	٥,	 -	0	-	-
P.02	LITER OXYGEN QUANTITY	D 2	0	0	2	-	0	-	-
P.03	AC FREQUENCY METER	17	0	0	17	-	0	-	16
P.04	AC VOLTMETER	7.	0	0	14	Ŋ	0	5	6
P.05	AIRSPEED	20	0	5	10	a	0	#	9
P.06	ANGLE OF ATTACK	8	0	0	~	-	0	 -	
P. 07	CABIN FLIGHT ALTITUDE	m	- -	0	N	0	0	0	8
30° d	CABIN PRESSURE DIFFERENCE	m	-	0	N	0	0	0	8
P.09	OIL TEMPERATU	m	0	0	m	0	0	0	m
P.10	OIL TEMPERATU	m	0	0	m	0	0	0	m
5,11	CSD3 OIL TEMPERATURE	m	0	0	m	0	0	0	m
P. 12	CSD4 OIL TEMPERATURE	*	,- -	0	m	0	0	0	m
-	DC VOLIMETER	2	0	O	N	0	0	0	7
-	ENGINE 1 EPR	7	0	۲	Ŋ	=	0	#	•
	ENGINE 1 FUEL FLOW	≉	0	0	#	7	0	~	8
F.17	ENGINE 1 N2 RPM	7	0	0	N	- -	0	-	-
P.18	ENGINE 1 OIL PRESSURE	#	0	0	#	m	0	m	- -
6	ENGINE 1 OIL TEMPERATURE	7	0	0	8	-	0	-	-
P.21	ENGINE 1 TIT	-	0	0	- -	-	0	•	0
P.22	ENGINE 2 FUEL FLOW	#	0	0	a	N	0	7	N ·
P.23	ENGINE 2 N2 RPM	7	0	0	8		0	-	- -
P.24	ENGINE 2 OIL PRESSURE	≉	0	0	#	m	0	ന	,
P.25	~	8	0	0	۷	-	0	-	 -
92	ENGINE 2 EPR	2	0	8	ហ	=	0	\$	-
P.29	ENGINE 2 TIT	-	0	0	۴	-	0	 -	0
P.30	ENGINE 3 EPR	7	0	7	വ	=	0	7	- -
31	ENGINE 3 FUEL FLOW	a	0	C	*	8	0	N	N
P.33	ENGINE 3 OIL PRESSURE	≉	0	0	4	m	0	m	,
P.34	ENGINE 3 OIL TEMPERATURE	8	0	0	N		0	- -	•
P.35	ENGINE 3 N2 RPM	7	0	0	N	-	0	 -	-
P.37	ENGINE 3 TIT	- -	0	0	,- -	+	0	 -	0

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Table 3. PARAMETER SIGNAL REQUIREMENTS (Concluded)

INDEX	PARAMETER	NUMBER SIGNALS	MALFUNC -TIONS	INITIAL /SETUP	AIRPLANE REQUIRED	MADAR	OTHER SOURCES	AVAIL -ABLE	UNAVAIL -ABLE
Œ	ENGINE 4 EPR	7	0	N	r	=	0	#	+-
(L)	⇉	ন	0	0	· #	m	0	m	-
щ	ENGINE 4 OIL TEMPERATURE	ત્ય	0	0	~	- -	0	-	-
121	ENGINE 4 FUEL FLOW	য	0	O	7	7	0	7	2
121	ENGINE 4 N2 RPM	8	0	0	N	-	0	-	 -
14	ENGINE 4 TIT	-	0	0	-	-	0	-	0
	FLAP POSITION INDICATOR	æ	8	-	w	8	0	8	m
_	LEFT MANIFOLD PRESSURE	Ŋ	0	0	ហ	m	0	m	8
_	LANDING GEAR LEVER	m	0	-	8	~	0	8	0
	LEFT APU EGT INDICATOR	*	0	0	#	8	0	~	8
_	MACH	ம	0	0	'n	2	0	~	m
	MAGNETIC HEADING	'n	0	-	ন	m	0	m	-
	MLG POSITION INDICATOR, LA	Ŋ	0	~	m	-	0		CI
	MLG POSITION INDICATOR, LF	5	0	~	m	-	0	-	7
	MLG POSITION INDICATOR, RA	5	0	8	m	•	0	-	٥
_	MLG POSITION INDICATOR, RF	S	0	7	ന	-	0		7
	NLG POSITION CROSSWIND IND	J.	0	8	m		0		0
_	NLG STEERING INDICATOR	80	~	m	m		0	•	α
	PITCH	9	0	_	ري ا	~	0	7	m
	RIGHT MANIFOLD PRESSURE	5	0	0	ς.	က	0	m	8
	RIGHT APU EGT INDICATOR	#	0	0	#	8	0	2	8
	ROLL	છ	0	~	4		0		m
	SYSTEM 1 HYDRAULIC PRESSURE	9	0	0	9	•	0	•-	Ŋ
	SYSTEM 2 HYDRAULIC PRESSURE	∞	0	0	ω		0	 -	7
	SYSTEM 3 HYDRAULIC PRESSURE	∞	0	0	ω	4	0		7
	≉	9	0	0	9	-	0	-	Ω
	YAW	7	0	0	7	-	0	_	-
	TOTAL	148	9	21	121	1 11	0	# #	77
•									

Table 4. NAVIGATIONAL FROFILE SIGNAL REQUIREMENTS

NAVIGATIONAL PROFILE	NUMBER SIGNALS	MALFUNC -TIONS	INITIAL	NUMBER MALFUNC INITIAL AIRPLANE SIGNALS -TIONS /SETUP REQUIRED MADAR	WAB	OTHER AVAIL UNAVAII SOURCES -ABLE -ABLE	AVAIL -ABLE	AVAIL UNAVAIL
INSTRUMENT DEPARTURE	41	0	6	32	#	10	#	18
	36	0	ω	28	,	σ	10	18
INSIRUMENT LANDING SYSTEM(ILS)	30	c	9	5₫	a	12	17	10
TOTAL	55	0	15	01	#	17	18	22

Table 5. SIGNAL REQUIREMENT SUMMARY

UNAVAIL -ABLE	363 77 23	¥04
AVAIL -ABLE	8 # # 6 # # 10	98
OTHER AVAIL UNAVAIL SOURCES -ABLE	0 0 15	1 1
MADAR	8 1 1	72
NUMBER MALFUNC INITIAL AIRPLANE SIGNALS -TIONS /SETUP REQUIRED MADAR	411 121 42	११६ ११
INITIAL /SETUP	2 12 15	
MALFUNC -TIONS	32	
NUMBER SIGNALS	448 148 57	
TASK	CHECKLIST MONITORABLE PARAMETER NAVIGATIONAL PROFILES	TOTAL

The simulator performance measurement system extracts data from the simulator system using a specially designed piece of equipment, the Data Acquisition and Control System (DACS). It allows the simulator PMS computer to acquire and control specific simulator data. The DACS serves to set up and control the simulator for a defined mission, insert and remove malfunctions, and monitor aircraw performance data. This technique makes it possible to monitor directly or indirectly all mission events that occur from the start of preflight to the termination of the mission, since all such event signal data are processed by the simulator computer and pass through a common input/output interface. A central processing interface of this nature does not exist on the C-5 aircraft.

At the initiation of the effort it was anticipated that the primary means of obtaining the required data would be through the MADARS. Subsequent investigation of the MADARS found it to be less than ideal for several reasons. The analysis of the currently available MADARS signals identified only two that were useable for performance monitoring. It would be possible to increase this number by adding additional signal acquisition units and modifying the MADARS program, but the airplane changes would be extensive. In addition, the extra workload on the MADARS computer could cause a degradation of current capabilities. Even more restrictive is the fact that the MADARS is not put into operation until the end of the Flight Engineer's Before Starting Engines checklist and is turned off at the beginning of the Flight Engineer's Engine Shutdown checklist. This completely precludes its ability to monitor crew performance during preflight and post-flight operations. The current MADAKS also limits the recording of trend operations, continually changing values, to ll per second. During periods of rapidly changing signals, such as takeoff and landing, signal values cannot be recorded as they change, but only when there is time. This would restrict the accuracy, timeliness, and usefulness of MADARS data.

Another approach would be the installation of a special processor/recorder unit to record the parameters required for crew evaluation. This would solve some of the restrictions of MADARS. The equipment could be designed such that it could be put into operation immediately by the flight engineer instructor on entering the aircraft and turned off just prior to exiting the airplane. This would allow the monitoring of the entire mission, including preflight and postflight. The processor selected would be powerful enough to sample and record all required signals at the correct frequency. A major problem still remains; namely, the extensive modifications to the C-5 airplane that must be made to acquire the signals. This is undesirable for two reasons. The major modifications involved in adding a PMS of this type could affect the qualifications of the aircraft flight readiness and could require extensive and expensive requalification. These modifications would be time-consuming to install and remove. The current plans are to utilize the Altus AFB training program as the source of performance measurement data. No C-5's are permanently assigned to Altus, but rather rotate there for a period of time. Therefore, a PMS system must be easy and quick to install and remove, thus effectively eliminating this approach.

At this point in the effort it was recognized that monitoring of all switch settings and mission events would be prohibitive. Therefore, the effort was redirected toward defining an airborne PMS mission that utilized the signals previously identified as available.

Airborne Navigational Profile Mission

An analysis was performed on each task of the full airborne nominal mission to determine the effect of missing signals on the ability of PMS to perform a meaningful measurement of crew performance related to that task. The results of this analysis are presented below, along with the specification of an Airborne PMS Navigational Profile Mission.

The normal checklists specified in the full airborne nominal mission require the acquisition of a large number of airplane signals to monitor the execution of all steps of the checklists. A comparison of the required signals and the available signals for each checklist shows that there are no checklists that can be completely monitored. In fact, most checklists are very sparse in the number of available signals present. Therefore, given the restrictions on extraction of airplane data, it is impossible to perform a meaningful measurement of aircrew performance in the execution of checklists.

The same type of analysis of the PMS standard list of monitorable parameters gives a similar result. With one instrument group of exceptions, no monitorable parameter definition has a sufficient number of available signals to give a meaningful analysis of crew performance. Therefore, the complete PMS standard parameter list cannot be monitored.

The final category of crew task performance comprises the execution of maneuvers related to departure, approach, and a landing. These are referred to in PMS as navigational profiles. The preliminary examination of the signals required for navigational profile monitoring also showed a large number of missing signals. Table 6 summarizes the signal requirements for this monitoring. A further analysis was performed which ranked the required signals in the order of relative importance. In addition, a further search was performed for sources for the signals with a high degree of importance. A study was then conducted on the effect of the remaining missing signals on navigational profile measurement. The result of this effort was that it is feasible to monitor navigational profiles and provide a meaningful measurement of crew performance. It was further determined that it was feasible to measure a small number of monitorable parameters related to the execution of navigational profiles.

Based on the analysis above, a new PMS nominal mission was defined and is presented in Appendix C. This nominal mission stresses the measurement of crew performance of navigational profiles. The monitoring of checklists and the standard parameter list has been removed. A small number of monitorable parameters related to the execution of navigational profiles has been added. An important point to note in this nominal mission is that there are no longer any tasks being monitored which relate to the Flight Engineer. The navigational profile nominal mission measures only a portion of the

Table 6. NAVIGATIONAL PROFILE MISSION SIGNAL REQUIREMENTS

NAVIGATIONAL PROFILE SIGNAL REQUIREMENTS

	NAVIGATIONAL PROFILE	NUMBER	MALFUNC -TIONS	INITIAL	AIRPLANE REQUIRED MADAR	MADAR	OTHER SOURCES	AVAIL -ABLE	UNAVAIL -ABLE
	INSTRUMENT DEPARTURE INITIAL APPROACH INSTRUMENT LANDING SYSTEM(ILS)	#1 36 30	000	O-80 VO	35 54 58 54 54 54 54 54 54 54 54 54 54 54 54 54	# - 0	10 12	± 0 ±	8t 6 C
	TOTAL	51	0	72	36	#	14	80	18
		PARAMETE	PARAMETER SIGNAL REQUIREMENTS	. REQUIRE	EMENTS				
THDEX	PARAMETER	NUMBER SIGNALS	NUMBER MALFUNC IGNALS -TIONS	INITIAL	INITIAL AIRPLANE /SETUP REQUIRED MADAR	MADAR	OTHER SOURCES	AVAIL -ABLE	UNAVAIL -ABLE
P.05	AIRSPEED	50	c	5	-	4	c	a.	¥
P.06	ANGLE OF ATTACK	i		2 c	۰ ۵	•	o c	٠.	•
P.47	FLAP POSITION INDICATOR	· cc	~	·	ו יע	- N	. 0	- ~	- rr
P.52		α	0	0	, CJ	•	0)
P.53	LEFT LANDING LIGHT SWITCH	-	0	0	-	0	0	ح .	-
P.55	LANDING GEAR LEVER	m	0	-	· N	N	0	· ~	. 0
P.69	NLG STEERING INDICATOR	œ	~	m	m	-	0	-	o Od
P.70	NOSE LANDING LIGHT SWITCH		0	0	·	0	o	0	-
P.71	PITCH	9	0	-	ısı	~	*	~	~
P.72	RIGHT LANDING LIGHT SWITCH		0	0	-	0	C)	0	-
P.75		ø	0	ય	7	_	0	_	(*)
P.83	VERTICAL SPEED	8	0	0	ಣ	- -	0	-	٠-
. a.	YAW	Q	0	0	~	•	0	-	*
	TOTAL	35	#	12	19	rc	-	9	13
		SIGNAL REQUIREMENT	equ ireme	NT SUMMARY	RY				
	TASK	NUMBER	MALFUNC -TIONS	INITIAL /SETUP	NUMBER MALFUNC INITIAL AIRPLANE IGNALS -TIONS /SETUP REQUIRED MADAR	MADAR	OTHER	AVAIL -ABLE	UNAVAIL -ABLE
	MONITORABLE PARAMETER NAVIGATIONAL PROFILES	35	# 0	5 5 7	19 36	ខាង	1 14	6 18	13 18
	TOTAL				25	7	14	21	31

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performance of the copilot: that part related to flying the airplane on predetermined flight plans for takeoff, approach, and landing.

Navigational Profile Mission Signal Requirements

In order to monitor crew performance within navigational profiles and associated monitorable parameters, the airborne PMS must acquire airplane data in six categories. The categories and their data variables are:

- 1. Present aircraft position:
 Latitude
 Longitude
- 2. Aircraft flight parameters:

 Altitude
 Altitude above ground level
 Airspeed
 Ground speed
 Vertical speed
 Rate of turn
 Magnetic heading
 Angle of attack
 Wheels on ground indicator
 Course Deviation Indicator (CDI)
 Glideslope Deviation Indicator (GSI)
 CDI Warning
- 3. Instrument Settings:
 Course set
 Navigation Selection Panel

GSI Warning

- 4. Control Settings:

 Flap handle

 Flap position indicator

 Landing gear lever

 Nose landing gear indicator

 Nose landing gear steering indicator
- 5. Flight command signals:

 Benk

 Fitch

 Roll

 Yaw
- 6. Navigational aid signals:
 ADF frequency
 ADF function switch
 TACAN DME
 TACAN channel
 TACAN mode switch
 TACAN function switch

TACAN antenna switch VOR frequency VOR switch

Data Storage Requirements

The redefinition of the airborne nominal mission to a navigational profile mission reduced the measurement capability of the PMS. In addition, it also reduced the storage requirements for data being extracted from the airplane. The data storage requirements were recomputed based on the new set of required parameters and are shown in Table 7.

Table 7. NAVIGATIONAL PROFILE MISSION DATA STORAGE REQUIREMENTS

% items	Number	Number		Number of	bytes per	item
changing in .8 sec		of items in 4 hours	3	4	5	6
1	1	10,080	30,240	40,320	50,400	60,480
2	1	20,160	60,480	80,640	100,800	120,960
3	2	30,240	90,720	120,960	151,200	181,440
4	2	40,320	120,960	161,280		241,920
5	3	50,400	151,200	201,600	252,000	302,400
10	6	100,800	302,400	403,200	504,000	604,800
25	14	252,000	756,000	1,008,000	1,260,000	1,512,000
50	28	504,000	•		2,520,000	•
75	42	756,000			3,780,000	
100	56	1,008,000			5,040,000	

Alternative Design Approaches

Phase I of the effort and the early part of Phase II were directed to defining the requirements and capabilities of an airborne PMS. Phase II culminated with the definition of alternate design approaches for the airborne PMS. The airborne PMS is composed of two distinct systems: the airborne recording system and the ground-based processing system. The options investigated for each system are discussed separately and their combinations are considered.

Airborne Recording System. Although the conclusion was reached that it is not feasible at this time to record all the signal values required for the full airborne nominal mission, the options available to do this recording were considered. To obtain all the required signals would require extensive changes to the C-5. A connection would have to be made to each location (switch, instrument, subsystem) generating a required signal. Each location would then be wired to a central source for sampling by a computer system, either MADARS or a new system. Practical considerations would dictate a new, powerful computer system. The output of this system

could take several forms such as raw recorded data, converted data, or fully processed performance data. These data could be transferred to the ground processing system on magnetic tape, disk, or even via a data link.

The airborne recording system required for the Navigation Profile mission is much simpler in nature. This system requires the extraction of a small amount of data from a limited number of sources. This system would have a breakout connector to the INS, the FDC, and MADARS. A simple keyboard would be required for instructor entries to identify the type of profile being flown. The processor would require enough capability to sample these sources of data periodically, format the data, and record the data on a transfer medium, probably magnetic tape.

Ground-Based Processing System. The choice of a ground-based processing system is directly related to the choice of the airborne recording system. Basically, the ground processing system would receive and process the recorded data to produce summary measures comparable to those produced by the simulator PMS. The ground-based system would process essentially as the simulator PMS does. The salient difference is that the source of data is the airborne recorded data rather than the simulator extracted data.

For all practical purposes, the current simulator PMS equipment can do this processing. An input device must be added to access the recorded data. The system will require software modifications and additions to process the airborne data properly. If, as for post-mission debriefing, rapid results are required, a duplicate of the PMS hardware suite can be used.

Recommended Design Approach. An interim briefing was held at the end of Phase II to present the findings of the study to AFHRL and Altus AFB personnel. The result of this briefing was the choice of a processing system and design approach for the airborne performance measurement system. The concept of the Navigational Profile mission was approved. A significant decision was to eliminate the requirement to support Altus training needs since the provided support appeared minimal. This decision relieved the timeliness requirement of the ground-based system and allowed the utilization of the simulator PMS equipment on an as-available basis.

A block diagram of the recommended system is given in Figure 1. This diagram illustrates the hardware elements of an airborne performance measurement system. The next section of this report will present a design specification for this system.

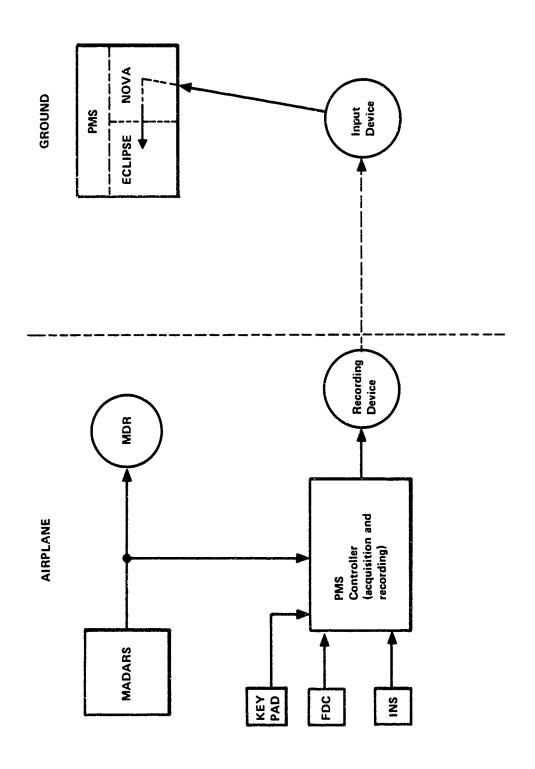


Figure 1. Recommended Airborne PMS System.

SECTION IV

PHASE III - SYSTEM DESIGN

The first two phases of this study were concerned with the investigation of the requirements for an airborne performance measurement system for C-5 aircrew members and with a search of current airplane systems for recorded and/or available signals to support these requirements. These two phases resulted in a refinement of the functional requirements for the airborne PMS and in the selection of the overall design for the airborne PMS. The task of phase III was to specify the detailed design of the selected configuration.

Airborne Performance Measurement System Requirements

The C-5 airborne performance measurement system should provide the capability to record data extracted from airplane systems. The data recorded should be sufficient to allow a computer system to analyze the data and provide a measurement of aircrew performance related to the task of flying profiles during the takeoff and landing phases of flight operations. The output of the airborne PMS should be in a format compatible with that currently output by the simulator PMS to allow comparison of equivalent indices of performance measurement.

Four factors will be considered for the airborne PMS design. The changes to the C-5 aircraft should be as few as possible. The airborne recording portion should be portable and require a minimum amount of effort to install and remove. The workload imposed on the instructor should be minimal. Lastly, the ground-based portion should utilize the current simulator PMS.

Airborne PMS System Design

The airborne PMS will be composed of the airborne recording system and the ground-based processing system. The interface between these two subsystems will be a medium for transferring data recorded in the airplane to the ground for processing. This concept is illustrated in Figure 2.

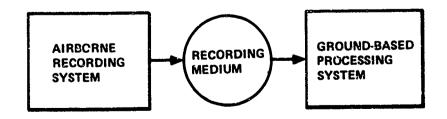


Figure 2. Airborne PMS Subsystems.

The following sections will describe the functional, hardware, and software requirements of these two subsystems.

Airborne Recording Design Specification

The airborne recording system will be designed as an attachment to the C-5 airplane. The design will ensure that there is no interference to the airplane operation or safety. The system will allow for easy installation and removal for utilization on several C-5 airplanes.

<u>Functional Requirements</u>. The functional requirements of the airborne PMS are defined based on four criteria:

- 1. The necessary aircraft signal data
- 2. The means to acquire and record these signals
- 3. The sampling rate for each signal
- 4. The means whereby appropriate instructor annotation can be made

Section III of this report defined a list of signal data that must be acquired from the C-5 to monitor and measure crew performance related to navigational profiles and associated monitorable parameters. It was determined that not all of these signals are readily available from C-5 subsystems. Analysis also determined that the missing signals would not adversely affect the ability to measure crew performance as defined by the airborne navigational profile mission.

The following signals can be obtained from the indicated airplane subsystems:

Inertial Navigation System (INS)
Bank
Latitude
Longitude
Roll

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Flight Director Computer (FDC)
Course Deviation Indicator (CDI)
CDI Warning
Glideslope Deviation Indicator (GSI)
GSI Warning
Navigational Select Panel
Pitch
TACAN DME

Malfunction Detection, Analysis, and Recording System (MADARS)
Flap Position Indicator
Landing Gear Lever
On-Ground Indication

The above data will be sampled at a rate of 0.8 second to remain compatible with the ground-based processing system cycle rate. The data will be recorded whenever a change is detected, although it should be permissible to define

a delta change for each parameter before recording takes place. All recorded data will be mission time-tagged.

A means will be provided for the instructor to annotate or identify the output data. This annotation will be limited to identification of the type of approach being flown.

Hardware Requirements. The hardware for the airborne recording system must be rugged, portable, and easily removed and installed. The system must not affect any of the aircraft systems to which it may be attached, either directly or indirectly. In operation, the system must require a minimum of intervention on the part of the instructor. An analysis of the functional requirements developed the following suggested hardware design. The hardware consists of five major units. A block diagram of the hardware is illustrated in Figure 3. The hardware subsystems are:

- 1. PMS Controller
- 2. Cartridge Tape Drive
- 3. Instructor Keypad and Display
- 4. MADARS Tape Interface (MIL-1553B)
- 5. INS and FDC Breakout Lines

The PMS Controller is the actual airborne processor responsible for acquiring and processing all data for later use. It will receive inputs from the instructor keypad, the FDC, the INS and the output of the existing MADARS system (obtained between the MADARS system and the MADARS tape drive).

The controller will be mounted in an aluminum instrument case, which will also contain the cartridge tape drive and provide a storage area for interface cables and the instructor keypad. The controller will consist of the following six functional units as illustrated in Figure 4:

- 1. Single Board Computer. A 16-bit computer which will perform data trending, I/O control, data formatting and related processing tasks for the airborne PMS controller.
- 2. Tape I/O Controller. This unit performs all "housekeeping" tasks related to the cartridge tape drive, such as Start, Stop, Record, etc.
- 3. Serial I/G. This unit performs all communication between the PMS controller and the Instructor Keypad.
- 4. FDC I/O. This unit receives data from the FDC breakout connection and converts the data into a format acceptable to the single board computer. Additionally, it serves to provide isolation between the controller and the FDC.
- 5. INS I/O. This unit receives data from the INS breakout connection and converts the data into a format acceptable to the single board computer. Additionally, it serves to provide isolation between the controller and the INS.

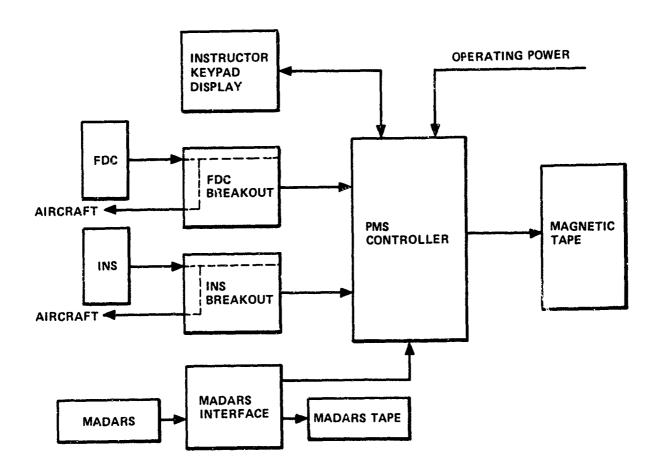


Figure 3. Airborne Recording System Hardware Block Diagram.

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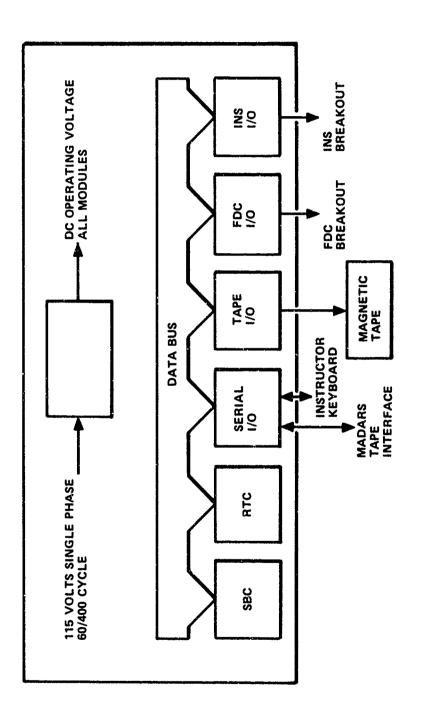


Figure 4. PMS Controller Block Diagram.

6. Real Time Clock (RTC). This unit provides the ability to time events to a high degree of accuracy, providing date and time information.

The above units all communicate over a high speed data bus and are physically located in the same card cage assembly, which, in turn, is located in the instrument case. A power supply to provide the required operating voltages for the components is also mounted in the case. The PMS controller will operate on aircraft power or ground power, 115 volts, 60 or 400 cycles, as required. During use of the system, the instrument case containing the controller will be placed in the luggage bay aft of the number two avionics bay. Cables will be run from the controller to the avionics bays for data acquisition.

The cartridge tape drive is used to provide a medium for storing the processed data and, additionally, as a method of transporting the data to the ground-based PMS system via the tape cartridge. The data from the PMS controller are stored on the magnetic tape as individually addressable blocks. The unit is mounted in the instrument case with the PMS controller and interfaces with the controller via the tape I/O unit. A cartridge tape unit was chosen for this application because of the general ruggedness of the unit, the small size, and the amount of storage. Additionally, the tape drive is easily interfaced to both the proposed airborne and the existing simulator PMS systems.

The instructor keypad and display is a small unit designed for handheld or tabletop use. It provides a means for the instructor to record information concerning the mission on the PMS tape. In this regard, it is similar to a CRT terminal in a computer system and, in fact, can be replaced by a CRT should the need arise. The unit consists of a keypad similar to the one used in the simulator PMS, and a small liquid crystal display with backlighting for night viewing. It communicates with the PMS controller via a serial data line and is stored in the instrument case when not in use.

The MADARS tape interface serves as the means by which the PMS controller obtains data from the MADARS system. Since the MADARS system communicates with its dedicated magnetic tape system using the MIL-1553B interface standard, this interface will serve as a "listen only" terminal in accordance with MIL-1553B. In this manner, any data sent to the MATARE magnetic tape unit will also be available to the PMS controller.

The MADARS tape interface will be installed in the avionics bay, near the MADARS tape unit. The cable to the tape unit will be removed and connected to the interface, and a short jumper cable will be connected from the interface unit to the tape unit. It is important to note that the MADARS-to-tape data path passes straight through the interface upit, and thus, the MADARS data recorded on tape are unaffected. There will be a cable from the interface unit to the PMS controller.

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The FDC and INS breakout connections are similar in design, function and use; therefore, this description applies to both. The data required from the FDC and INS systems are not directly available at any location in the aircraft. A study of the C-5 configuration indicated that the easiest method of obtaining the requisite data was to tap into the lines at the This is done by use of the "breakout" connector. actual FDC and INS. Simply stated, the breakout connector is inserted between the equipment and its present connection to the aircraft. As in the MADARS tape interface, the connection from the FDC or INS to the remainder of the aircraft remains unchanged, but the data are available to the PMS controller via the parallel tap of the breakout. The connectors used would be the same as the type presently used in the Airline Transport Radio (ATR) mounts for the equipment. No signal conditioning is performed at this point since all signal processing and isolation are performed by the FDC and INS I/O irterfaces in the PMS controller.

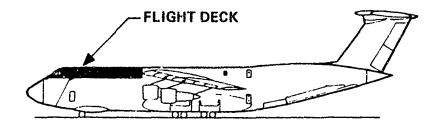
Aircraft Changes. The airborne PMS system is designed to have minimal impact on the operation of the aircraft. Additionally, the system requires no permanent physical or electrical changes to the aircraft. The system will operate on 115 volts AC, single phase, 60 or 400 cycles. Installation consists of placing the PMS controller in the small luggage compartment aft of avionics bay #2, installing the breakout connectors on the INS, FDC, and MADARS tape, routing the interconnecting cables and applying operating power. A more detailed description of equipment location and installation methods is provided below.

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The controller unit will be placed in the luggage bay aft of the avionics bay, as shown in Figure 5, and will require no further attention after power is applied and the system is initialized. Data cables are run from the controller to the breakout connections. Access is available for cable routing from the luggage compartment to the two avionics bays without physical modification of the aircraft. The controller is physically secured by the use of tie-down straps in the compartment. As an alternative, the PMS controller can be located in the #2 avionics bay, in existing blank space on the equipment shelves. In the aircraft surveyed at Altus AFB, sufficient room existed for installation in either location, with no interference to normal aircraft operation.

The only physical modification required for the installation of the PMS was the installation of the breakout connectors in the FDC and INS equipment mounts. The breakout connection is essentially a line tap, which provides a method of obtaining data not otherwise available in the aircraft. The following description is generalized and applies equally to the FDC and the INS system.

Figure 6 shows a typical aircraft equipment mount and a representative piece of electronic gear. Of particular importance is the location of the connector area in the rear of the equipment mount. The breakout connector assembly is shown in Figure 7. The breakout connector is installed by



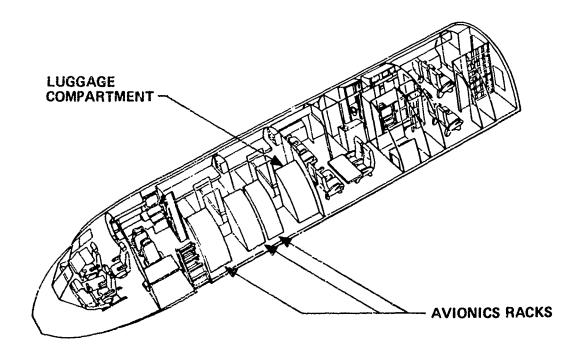


Figure 5. Equipment Areas.

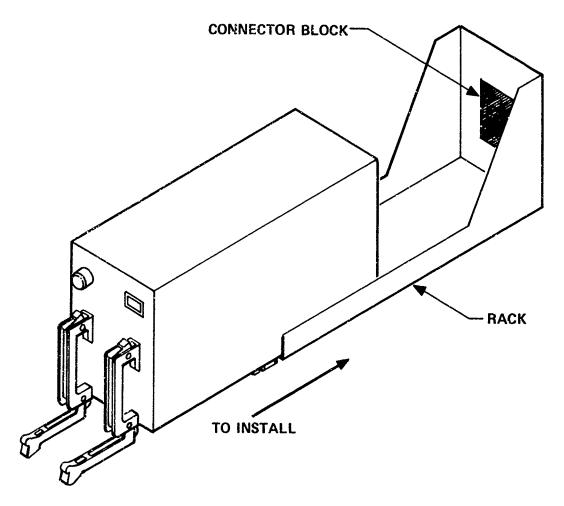


Figure 6. Typical Equipment and Rack Mount.

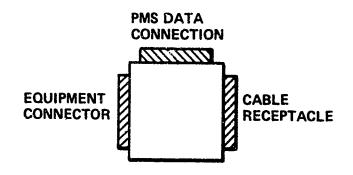


Figure 7. Breakout Box.

removing the original connector from the equipment mount, as shown in Figure 8. The new breakout connector is installed on the equipment mount in place of the original connector. The original connector is then attached to the breakout connector. The relationship of the components (equipment mount, breakout, and connector) are shown in the exploded view, Figure 9.

The same approach is utilized in interfacing to the MADARS tape unit. The connection between the MADARS and the MADARS tape is removed at the tape unit, and a breakout connection similar to the one utilized for the FDC or INS systems is inserted in the line. This serves to make data from the MADARS available to the PMS controller for analysis.

Software Requirements. The software for the airborne recording system will control the microprocessor in the acquisition and recording of airborne signal data. A block diagram of the required functions is shown in Figure 10. The following discussion describes the function of each block:

- 1. FDC, INS, MADARS Data Extraction. These three modules provide the interface with the C-5 systems. They will sample the data provided by the systems and extract those signals required by PMS.
- 2. <u>Data Conversion</u>. This module will take the raw signals from the data extraction routines and convert them into a standard digital format usable by the ground-based processing system.
- 3. <u>Keyboard Input</u>. This module will monitor the instructor keyboard entry device and interpret any entries made by the instructor.
- 4. <u>Time Maintenance</u>. This module will utilize a hardware real-time clock to maintain a mission clock.
- 5. Data Formatting. This module will format data packets for use by the ground-based system. Each packet will be made up of a data type identifier, mission time, and data (airplane extracted or instructor entered).
- 6. <u>Buffer Management</u>. This module will maintain a set of double buffers to prepare records of data for output to the recording device.
- 7. <u>Data Output</u>. This module writes the buffers of data to the recording device.

Ground-Based Design Specification

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The ground-based portion of the C-5 airborne PMS will use the hardware and software of the simulator PMS. This hardware and software will be expanded and modified to accomplish the requirements of the airborne PMS,

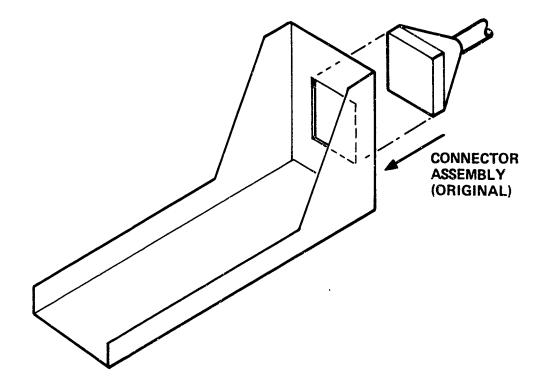


Figure 8. Equipment Mount Connector Location.

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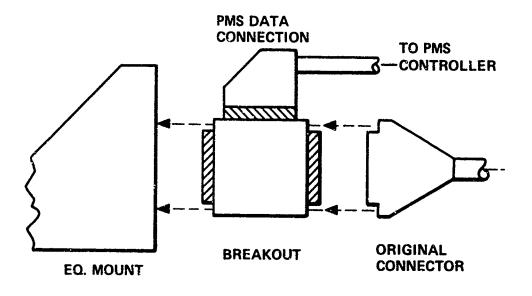
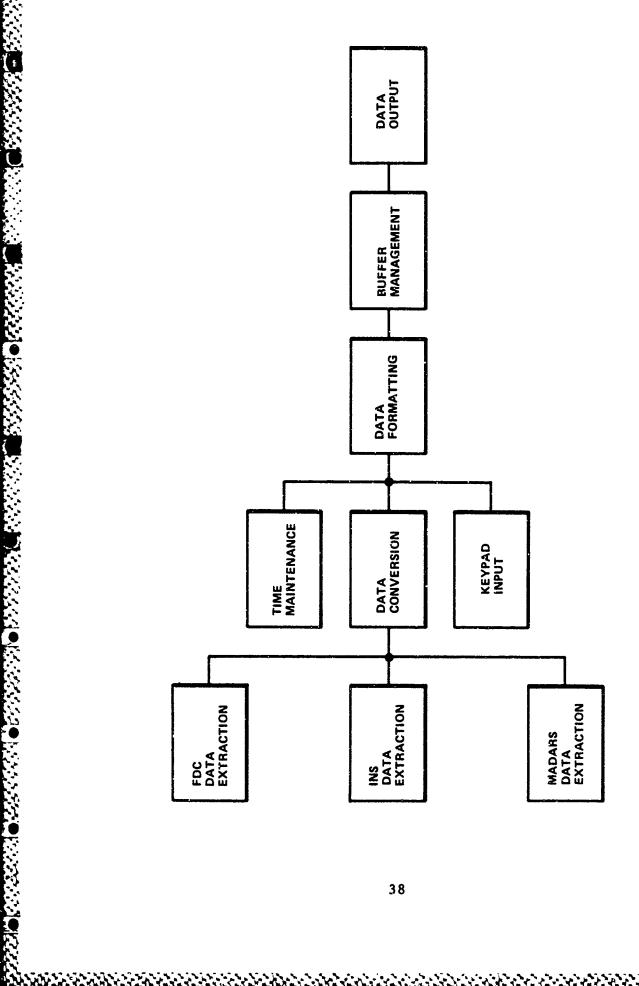


Figure 9. Exploded Installation Diagram.



Airborne Recording System Software Functions. Figure 10.

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<u>Functional Requirements</u>. The ground-based portion of the airborne PMS will process the recorded data from the airborne recording system and produce outputs equivalent to the simulator PMS. To accomplish this, it will perform the following functions:

- 1. Pre-process airborne recorded data (i) to extract data related to navigational profile monitoring, (ii) to mark start and end of navigational profiles, and (iii) to format input for the PMS monitor program
- 2. Perform performance measurement of airborne data
- 3. Provide performance data for statistical analysis

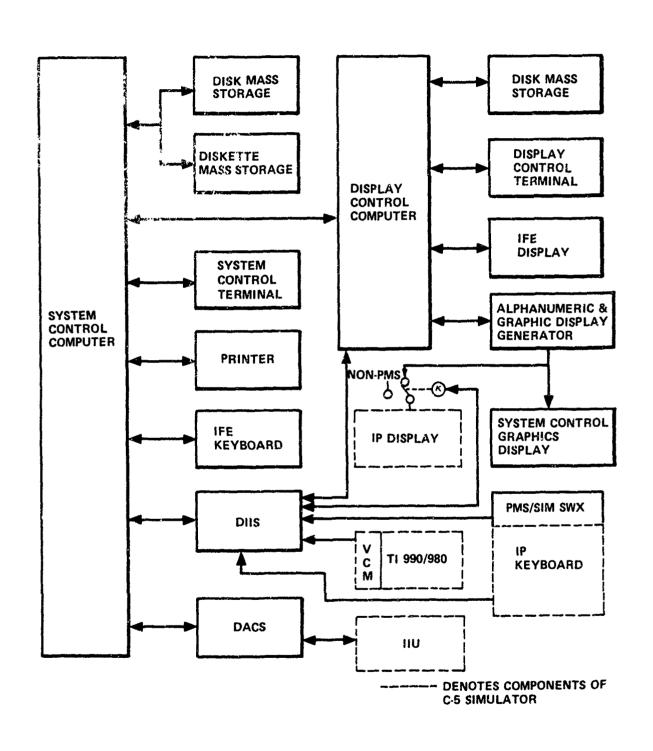
Hardware Requirements. The ground-based processing system will contain the hardware required to support the functional requirements. The study has shown that the simulator PMS possesses the computational power and peripherals to fulfill this need. The exception to this is a tape unit to interface with the airborne recording system. A block diagram of the current simulator PMS is shown in Figure 11. A block diagram of the ground-based system is shown in Figure 12. The shaded blocks of Figure 12 are components which must be added to the simulator PMS to accomplish ground-based processing.

The hardware divides into two systems connected by Multiprocessor Communications Adapter (MCA) Interfaces. The simulator Display Control Computer system will function as the interface to the airborne recording system. As such, it will be augmented by the attachment of a magnetic tape unit and associated controller. The sole function of this system is to read airborne data from the tape and pass these data to the System Control Computer via the MCA. The Display Control Terminal serves as the operator interface while the Disk Mass Storage provides programs and intermediate storage.

The System Control Computer hardware supports the processing of airborne performance data. It requires no additional hardware from that provided by the simulator PMS hardware suite. The System Control Computer provides the computational requirements of the system, which are less than those required for the simulator PMS. The System Control Terminal serves as the operator interface. The disk mass storage provides programs and data storage. The printer provides hardcopy of the various performance measure outputs.

The hardware components of the simulator PMS which will be utilized by the ground-based processing system are:

1. System Control Computer - Data General Corporation Eclipse S/130 general purpose mini-computer with 512 kilobytes (KB) of memory. The following additional circuit boards are a part of the computer system:



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Figure 11. C-5 Simulator PMS Block Diagram.

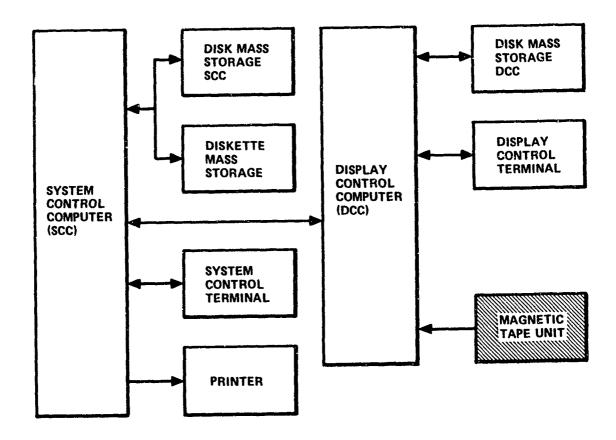


Figure 12. Ground Processing System Block Diagram.

- a. Memory Allocation and Protection Unit (MA!')
- b. Floating Point Instruction Set
- c. Multiprocessor Communications Adapter (MCA)
- d. Real-Time Clock
- e. Disc Controller I/O Board
- f. Four Channel I/O Board
- 2. Disk Mass Storage (SCC) Data General Corporation Model 6045 disk unit containing 10 megabytes (MB) of storage
- 3. Diskette Mass Storage Data General Corporation Model 6030 dual diskette unit, each with 308 kilobytes (KB) of storage
- 4. System Control Terminal Micro Term Inc., Model MIME II CRT/keyboard terminal with a 12-inch diagonal CRT display, a 65-key keyboard, and a 12-key auxiliary numeric keypad.
- 5. Printer Printronix Model P-600 printer

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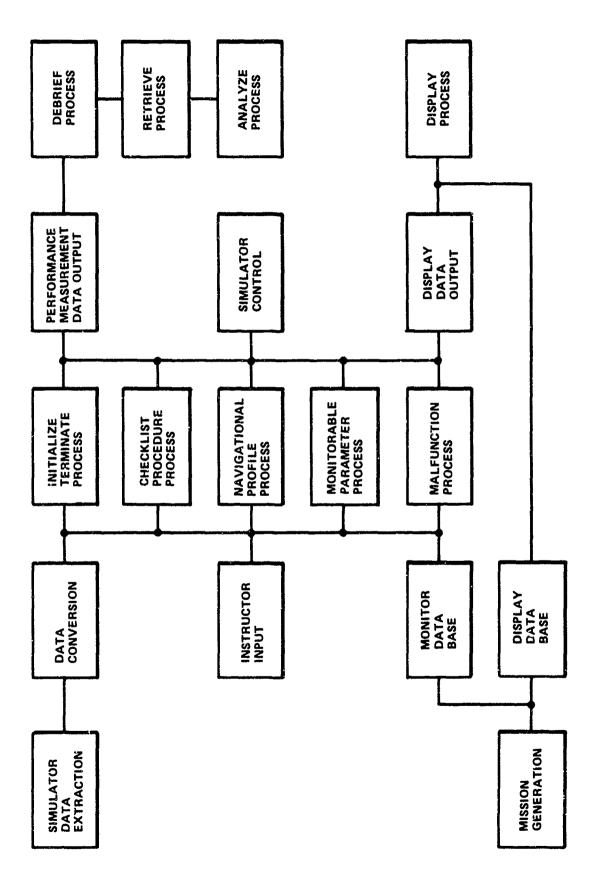
- 6. Display Control Computer Data General Corporation Nova 4/S general purpose mini-computer with 64 kilobytes (KB) of memory. The following additional circuit boards are a part of the computer system:
 - a. Multiprocessor Communications Adapter (MCA)
 - b. Disc Controller I/O Board
 - c. Four Channel I/O Board
- 7. Disk Mass Storage (DCC) Data General Corporation Model 6045 disk unit containing 10 megabytes (MB) of storage
- 8. Display Control Terminal Micro Term Inc., Model MIME II CRT/keyboard terminal with a 12-inch diagonal CRT display, a 65-key keyboard, and a 12-key auxiliary numeric keypad.

The hardware components which must be added to the simulator PMS to support ground-based processing are:

- 1. Magnetic Tape Controller connected to the Display Control Computer, an off-the-shelf controller to interface the magnetic tape unit
- 2. Magnetic Tape Unit A standard cartridge tape drive, similar to the tape drive in the airborne recording system

Software Requirements. The software for the ground-based processing system will use the simulator PMS software as a basis for software development. The majority of the main software modules are identical to the simulator PMS, especially in the later steps of processing. A block diagram of the main software functions of the simulator PMS is shown in Figure 13. A corresponding block diagram of the ground-based processing system software functions is shown in Figure 14. The following discussion describes the function of each block of Figure 14 and identifies the commonality with simulator PMS software.

- 1. Airborne Data Preprocessing. The airborne recorded data will be provided to the ground-based system on magnetic tape in a continuous stream from the start of the mission to the end. As such, the tape will contain a large amount of data not related to the segments being considered for performance measurement. This new module will execute as a stand-alone program. It will read the airborne data tape, identify the start and end of relevant navigational profiles, and extract the data associated with them. This extracted data will be placed in a disk file for use by the real-time PMS software.
- 2. Mission Generation. This program processes mission designer inputs and produces a monitor data base for use by the real-time performance measurement modules and a debrief data base for use by the Debrief program. No change is anticipated to this existing simulator PMS program.



Simulator Performance Measurement System Software Functions. Figure 13.

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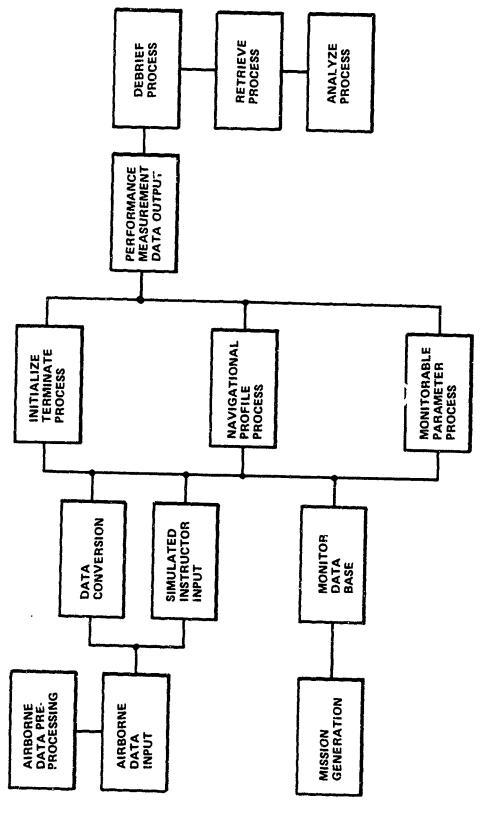


Figure 14. Ground-Based Processing System Software Functions.

- 3. Airborne Data Input. This will be a new module for the ground-based processing system. It replaces the simulator data extraction interface. It reads the disk file of preprocessed airborne data and inserts the data into the real-time monitor data base at the appropriate mission times for processing of performance measures.
- 4. <u>Data Conversion</u>. This module will provide the same function as the simulator data conversion module, but a new set of conversion algorithms must be developed. The data outputs of this module are used by the measurement modules.
- 5. Simulated Instructor Input. This new module will process data from the preprocessed airborne data file associated with mission control, including start/stop mission and start/stop navigational profile. This module will cause the real-time measurement software to operate in the manual mode.
- 6. <u>Initialize/Terminate Process</u>. This module is responsible for the setup, initialization and termination of the PMS system. It initializes all devices, reads the monitor data base and initializes the real-time modules. Although portions of the simulator PMS programs can be used, a major portion of this module will be new development.
- 7. Navigational Profile Process. This module is the major real-time process for the ground-based system. It will process the navigational profile related data from the airborne system and provide performance data for the post-mission processes. The simulator PMS navigational profile module will be used with some minor modifications. These relate to simulator control and to data that are not extracted from the airplane.

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- 8. Monitorable Parameter Process. This module provides performance measurement data for monitorable parameters. The simulator PMS module will be used without change.
- 9. <u>Performance Measurement Data Output</u>. This portion of the ground-based system is identical to that for the simulator PMS. It produces a mission log file of performance measures for use by the post-mission programs.
- 10. <u>Post-Mission Programs</u>. The post-mission programs developed for the simulator PMS will be used without change by the ground-based system. These are the Debrief, Retrieve, and Analyze processes.

The ground-based processing system software obtained from the simulator PMS will contain references to interfaces not utilized, such as the display computer, the Data Acquisition and Control Subsystem (DACS), and the Data Interception and Interrogation Subsystem (DIIS). These references will be aborted or severed at the highest level possible.

In addition to the changes associated with PMS processing, diagnostics will be provided for the new equipment. This involves two areas. The first is an equipment diagnostic for the magnetic tape unit and controller. The second involves modification of the Confidence program to test only the equipment associated with the airborne PMS ground-based processing system.

System Design Summary

The system design described in this section provides an airborne performance measurement system which allows AFHRL personnel to collect data on aircrew performance during portions of their flight training related to navigational profile flying. The data collected from these missions are identical in format and type to data collected from the simulator PMS. This allows comparison of equivalent indices of performance measurement.

It was a design goal to configure a ground-based system which utilized the existing simulator PMS hardware and software. In the airplane, the design goal was to provide portability and to use off-the-shelf components where possible. In the area of portability, the PMS equipment should be installable in less than 1 day and should have no effect on aircraft reliability. The majority of the hardware components are off-the-shelf items. The exceptions to this are the FDC, INS, and MADARS interface components.

An estimate of the development cost of the airborne PMS is given in Appendix I. The off-the-shelf components were chosen and costed based on what was available as of the date of this report. An implementation of this design should include a product survey of current components.

SECTION V

SUMMARY

The study of the requirements for an airborne PMS for the C-5 was conducted in three phases. This section will summarize these phases and discuss the implications of the results on future aircraft systems in relation to performance measurement.

In Phase I of the effort, the requirements for an airborne PMS were explored. This included identification of R&D and instructor needs as well as uses for training course developers. Through definition of an airborne nominal mission similar to an equivalent simulator PMS mission, the functional capabilities of the airborne PMS were identified. This phase included an identification of the C-5 systems available to provide performance data.

The results of this phase showed that a mission could be identified for the airplane which was equivalent to a mission defined for the simulator. The major area of difference was that no malfunctions were identified for the airborne system; consequently, emergency checklist would not be monitored. Three airplane systems were identified as being capable of providing signal data to be used for performance measurement. These were the MADARS, the Flight Director Computer (FDC), and the Inertial Navigation System (INS). These three systems provided approximately 86 of the required 494 signals for airborne measurement.

In Phase II, various alternatives were considered for providing airborne performance measurement. It was determined that extensive changes to the C-5 airplane would be required in order to acquire the signals not provided by the systems identified in Phase I. This was undesirable from several points of view, including cost, safety, and usability. Therefore, an alternative nominal mission was defined which utilized the readily available signals. This was called the Navigational Profile nominal mission and measured only performance in flying navigational profiles and in maintaining parameters associated with navigational profiles.

The various possible approaches to recording and processing the performance data were investigated. At the end of Phase II, a design was chosen which extracted data from airplane systems using an onboard microcomputer and a recording medium. These recorded data are then processed on the ground by a modified version of the existing simulator PMS.

Phase III produced a system design for an airborne PMS system. This design basically calls for the construction of interfaces devices to the MADARS, FDC, and INS. These devices are sampled by an onboard microcomputer

and the data is written to a magnetic tape unit. This onboard airborne recording system is operational from the start of a training mission until its completion.

The design also calls for the processing of this recorded data tape by a ground-based system. This system would be built around the current simulator PMS system, with the addition of a magnetic tape unit. The majority of the simulator PMS software would be used, with new software added to read and process the data from the tape as opposed to extracting data from the simulator. Programs related to debriefing reports, data retrieval, and data analysis would be identical to the simulator PMS.

The major drawback to producing an airborne PMS system for the C-5 proved to be in the area of data extraction. The C-5 wiring is organized in a point-to-point arrangement. This means that there is no central place where all the data are available. To extract the data required for full performance measurement would entail constructing many extraction devices and considerable airplane modification and additional wiring. This is prohibitive. For an airborne PMS to be completely useful, it must have access to large amounts of data from many sources. This requires a data passing interface organized on a data bus. The extraction hardware for the PMS would then interface to this bus and acquire whatever data it required.

With a system where the PMS had access to the full range of data, it would be possible to design an airborne PMS system which would be equivalent to the current simulator PMS. This would provide the data needed to assess such things as transference of training from the simulator to the airplane, to provide instructors with performance data, and to evaluate the effectiveness of course makeup. It would be constructive if future aircraft designs took into consideration the requirements for the measurement of crew performance and incorporated methods for easy extraction of all crew actions.

REFERENCE

Swink, Jay R., Butler, Edward A., Lankford, Harry E., Miller, Ralph M., and Watkins, Hal, "Definition of Requirements for a Performance Measurement System for C-5 Aircrew Members", AFHRL-TR-78-54, October 1978.

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GLOSSARY

This glossery defines terms and acronyms peculiar to aircraft systems and PMS which may be unfamiliar to the reader. These terms and acronyms are found throughout the body of the report.

A/I Anti-Ice

AC Alternating Current

ADF Automatic Direction Finding

AFHRL Air Force Human Resources Laboratory

ALDCS Active Lift Distribution Control Subsystem

APU Auxiliary Power Unit

ATR Airline Transport Ratio

CDI Course Deviation Indicator

CFT Cockpit Familiarization Trainer

CPT Cockpit Procedural Trainer

CSD Constant Speed Drive

DACS Data Acquisition and Control Subsystem

DC Direct Current

DCC Display Control Computer

DIIS Data Interception and Interrogation Subsystem

DME Distance Measuring Equipment

EGT Exhaust Gas Temperature

EPR Engine Pressure Ratio

FDC Flight Director Computer

FE Flight Engineer

GSI GlideSlope deviation Indicator

IFE Instructor Flight Engineer

INS Inertial Navigation System

IP Instructor Pilot

KB KiloByte - 1024 bytes

MAC Military Airlift Command

MADARS MAlfunction Detection, Analysis and Recording System

MB MegaByte - 1024 KB

MCA Multiprocessor Communications Adapter

MDR Maintenance Data Recorder

N1 Engine Fan RPM

N2 Engine High Pressure Compressor RPM

P Pilot; Pilot/Copilot

PAR Proficiency Assessment Records

PMS Performance Measurement System

RDF Retrieved Data File

RPM Revolutions Per Minute

RTC Real-Time Clock

SBC Single Board Computer

SCC System Control Computer

TACAN TACtical Air Navigation

TIT Turbine Inlet Temperature

VOR Visual Omni Range

APPENDIX A

AIRBORNE NOMINAL MISSION OVERVIEW

```
MISSION: ?
CREW: BOTH
SESSION 1:
SET-UP:
AIRCRAFT CONFIGURATION:
     OPERATING-WEIGHT
                                  777777
                                             LBS
     RAMP-FUEL
                                  ??????
                                             LBS
     CARGO/PAX
                                   ?????
                                             LBS
     CENTER - >F-GRAVITY
                                       ??
                                             2
                                      ???
     FUEL-MANAGEMENT
TOLD CARD WORKSHEET:
                                    ?.??
     EPR-TRT-STAT
     EPR-TRT-IF
                                    ?.??
     EPR-T/O-STAT
                                    ?.??
     EPR-T/O-IF
                                    ?.??
     TAKE-OFF-STAB-TRIM
                                    ?.??
     V-ROT
                                     ???
                                             KNOTS
     V-MCO
                                     ???
                                             KNOTS
     V-MFR
                                     ???
                                            KNOTS
     H-MFR
                                    ????
                                             FEET
     V-TLS
                                     ???
                                             KNOTS
     V-G0
                                     ???
                                             KNOTS
     XWIND-T/O-MAX
                                    ?.?
                                             DEG
     XWIND-T/O-MIN
                                    ?.?
                                             DEG
     XWIND-SETTING-T/O
                                     ?.?
                                             DEG
     XWIND-SETTING-LAND
                                      ?.?
                                             DEG
     FLT-ALT-MAX
                                   ?????
                                             FEET
     FLT-ALT-MIN
                                   ?????
                                             FEET
DEPARTURE INITIALIZATION:
                                                             ; ALTUS 35
                                  34 38.64 N
     INITIAL-LATITUDE
                                   99 16.52 W
     INITIAL-LONGITUDE
                                  ALTUS
     FIELD
     RUNWAY-IDENTIFIER
                                      35
                                     351
                                             DEG
     RUNWAY-HEADING
     FIELD-ELEVATION
                                    1378
                                             FEET
     ALTIMETER-SETTING
                                   ??.??
                                             IN HG
     RUNWAY-TEMPERATURE
                                             DEG C
     CRUISE-TEMPERATURE-DEVIATION
                                        ?
                                             DEG C
     WIND-DIRECTION
                                        ?
                                             DEG
     WIND-VELOCITY
                                        ?
                                             KNOTS
     WIND-GUSTS
                                  ??????
```

MONITORABLE PARAMETERS: STANDARD-LIST

BEFORE INTERIOR CHECK:

MONITOR "BEFORE INTERIOR" CHECKLIST

INTERIOR CHECK:

MONITOR "INTERIOR (1-15)" CHECKLIST
MONITOR "INTERIOR (16-30)" CHECKLIST
MONITOR "INTERIOR (31-37)" CHECKLIST
MONITOR "INTERIOR (38-60)" CHECKLIST
MONITOR "INTERIOR (61-66)" CHECKLIST
MONITOR "INTERIOR (67-73)" CHECKLIST
MONITOR "INTERIOR (74-80)" CHECKLIST
MONITOR "INTERIOR (81-105)" CHECKLIST

BEFORE STARTING ENGINES:

MONITOR "BEFORE STARTING ENGINES" CHECKLIST MONITOR "STANDARD FUEL MANAGEMENT" PROCEDURE

STARTING ENGINES:

MONITOR "STARTING ENGINES" CHECKLIST

BEFORE TAXI:

MONITOR "BEFORE TAXI" CHECKLIST

TAXI:

MONITOR "TAXI" CHECKLIST

BEFORE TAKE OFF:

MONITOR "BEFORE TAKE OFF" CHECKLIST

LINEUP:

MONITOR "LINEUP" CHECKLIST

TAKE OFF:

MONITOR "TAKEOFF THROTTLE SETTING" PROCEDURE

AFTER TAKE OFF CLIMB:

MONITOR "HOBART FIVE DEPT 35" DEPARTURE PROFILE

APPROACH:

MONITOR "APPROACH" CHECKLIST
MONITOR "ALTUS LOW ILS RWY 35" APPROACH PROFILE

BEFORE LANDING:

MONITOR "BEFORE LANDING" CHECKLIST

MONITOR "ALTUS ILS RWY 35" ILS-FINAL PROFILE

MONITOR "ALTUS TACAN 17" APPROACH PROFILE

MONITOR "BEFORE LANDING" CHECKLIST

MONITOR "ALTUS VOR DME RWY 35" APPROACH PROFILE

MONITOR "BEFORE LANDING" CHECKLIST

SESSION 2:

MONITORABLE PARAMETERS: STANDARD-LIST

BEFORE LANDING:

MONITOR "STANDARD FUEL MANAGEMENT" PROCEDURE
MONITOR "HOBART FIVE DEPT 35" DEPARTURE PROFILE
MONITOR "ALTUS LOW ILS RWY 35" APPROACH PROFILE
MONITOR "BEFORE LANDING" CHECKLIST
MONITOR "ALTUS ILS RWY 35" ILS-FINAL PROFILE
MONITOR "ALTUS TACAN 17" APPROACH PROFILE
MONITOR "BEFORE LANDING" CHECKLIST
MONITOR "ALTUS VOR DME RWY 35" APPROACH PROFILE
MONITOR "BEFORE LANDING" CHECKLIST
MONITOR "BEFORE LANDING" CHECKLIST
MONITOR "LANDING" PROCEDURE

AFTER LANDING:

MONITOR "AFTER LANDING" CHECKLIST

ENGINE SHUTDOWN:

MONITOR "ENGINE SHUTDOWN" CHECKLIST

BEFORE LEAVING AIRCRAFT:

MONITOR "BEFORE LEAVING AIRPLANE" CHECKLIST

CREW MEMBER ASSESSMENT:

SESSION 1;	PILOT:							
CHECK-PROC	MIN	Z	70	CRIT	FACT	0.95	WGT	1.0
NAV PROFL	MIN	7	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER	MIN	%	70	CRIT	FACT	0.95	WGT	0.9
SESSION 1;	COPILOT:							
CHECK-PROC	MIN	7	70	CRIT	FACT	0.95	WGT	1.0
NAV PROFL	MIN	%	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER	MIN	7	70	CRIT	FACT	0.95	WGT	0.9
SESSION 1;	FLIGHT ENGIN	EER	:					
CHECK-PROC	MIN	7	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER	MIN	7	70	CRIT	FACT	0.95	WGT	0.7
SESSION 1;	CREW COORDINA	ATI	ON:					
CHECK-PROC	MIN	7	70	CRIT	FACT	0.95	WGT	1.0
NAV PROFL	MIN	7	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER	MIN	Z	70	CRIT	FACT	0.95	WGT	0.7

SESSION 2; CHECK-PROC NAV PROFL PARAMETER		MIN	ጄ	70 70 70	CRIT	FACT	0.95 0.95 0.95	WGT	1.0 1.0 0.9
SESSION 2; CHECK-PROC NAV PROFL PARAMETER	COPILOT:	MIN	%	70 70 70	CRIT	FACT	0.95 0.95 0.95		1.0 1.0 0.9
SESSION 2; CHECK-PROC PARAMETER	FLIGHT E		%	70			0.95 0.95	WGT WGT	1.0
SESSION 2; CHECK-PROC NAV PROFL PARAMETER		RDIN MIN MIN MIN	% %	70 70	CRIT	FACT	0.95	wgt Wgt Wgt	1.0
SESSION ASS	ES SMENT:								
SESSION 1: PILOT COPILOT FLT ENGR CREW COORD			% %		CRIT CRIT	FACT FACT	0.95 0.95 0.95 0.95	wgt Wgt	
SESSION 2: PILOT COPILOT FLT ENGR		MIN	% %	70	CRIT CRIT CRIT	FACT FACT FACT	0.95 0.95 0.95	WGT WGT WGT	2.0 1.0 2.0
CREW COORD		MIN	*	70	CRIT	FACT	0.95	WGT	1.5
MISSION ASS	ESSMENT:								
SESSION 1 SESSION 2		MIN MIN		70 70		FACT FACT	0.95 0.95	WGT WGT	

APPENDIX B

SIMULATOR NOMINAL MISSION OVERVIEW

MISSION: ? CREW: BOTH					
SESSION 1:					
SET-UP:					
AIRCRAFT CONFIGURATION:					
OPERATING-WEIGHT	,	359000	LBS		
RAMP-FUEL		175000	LBS		
CARGO/PAX		0	LBS		
CENTER-OF-GRAVITY		39	Z		
FUEL-MANAGEMENT		ALTER	NATE		
TOLD CARD WORKSHEET:					
EPR-TRT-STAT		5.17			
EPR-TRT-1F		5.04			
EPR-T/O-STAT		4.77			
EPR-T/O-IF		4.64			
TAKE-OFF-STAB-TRIM		90			
V-ROT		121	KNOTS		
V-MCO		131	KNOTS		
V-MFR		156	KNOTS		
H-MFR		2378	FEET		
V-TLS		175	KNOTS		
V-GO		121	KNOTS		
XWIND-T/O-MAX		-3.0	DEG		
XWIND-T/O-MIN		3.0	DEG		
XWIND-SETTING-T/O		0.0	DEG		
XWIND-SETTING-LAND		0.0	DEG		
FLT-ALT-MAX		5000	FEET		
FLT-ALT-MIN		2378	FEET		
DEPARTURE INITIALIZATION:					
INITIAL-LATITUDE	•	34 38.64 N	l	: ALTUS	35
INITIAL-LONGITUDE		99 16.52	W	,	
FIELD		ALTUS			
RUNWAY-IDENTIFIER		35			
RUNWAY-HEADING		351	DEG		
FIELD-ELEVATION		1378	FEET		
ALTIMETER-SETTING		29.79	IN HG		
RUNWAY-TEMPERATURE		15	DEG C		
CRUISE-TEMPERATURE-DI	EVIATION	0	DEG C		
WIND-DIRECTION		180	DEG		
WIND-VELOCITY			KNOTS		
WIND-GUSTS	9	STEADY	-		
MONITORABLE PARAMETERS:					
STANDARD-LIST					

BEFORE INTERIOR CHECK:

MONITOR "BEFORE INTERIOR" CHECKLIST

INTERIOR CHECK:

MONITOR "INTERIOR (1-15)" CHECKLIST
MONITOR "INTERIOR (16-30)" CHECKLIST
MONITOR "INTERIOR (31-37)" CHECKLIST
MONITOR "INTERIOR (38-60)" CHECKLIST
MONITOR "INTERIOR (61-66)" CHECKLIST
MONITOR "INTERIOR (67-73)" CHECKLIST
MONITOR "INTERIOR (74-80)" CHECKLIST
MONITOR "INTERIOR (81-105)" CHECKLIST

BEFORE STARTING ENGINES:

MONITOR "BEFORE STARTING ENGINES" CHECKLIST MONITOR "STANDARD FUEL MANAGEMENT" PROCEDURE

STARTING ENGINES:

MONITOR "STARTING ENGINES" CHECKLIST

BEFORE TAXI:

MONITOR "BEFORE TAXI" CHECKLIST

TAXI:

MONITOR "TAXI" CHECKLIST

BEFORE TAKE OFF:

MONITOR "BEFORE TAKE OFF" CHECKLIST

LINEUP:

MONITOR "LINEUP" CHECKLIST
WHEN P-IAS GE 121 THEN
BEGIN
ENTER MALFUNCTION 350
ENTER MALFUNCTION 010
FND.

MALFUNCTION TEXT: "WHEN AIRSPEED EXCEEDS 121 KCAS"
MALFUNCTION TEXT: "ENTER MALFUNCTION 350"
MALFUNCTION TEXT: "ENTER MALFUNCTION 010"

TO THE PROPERTY OF THE STREET WAS CONTRACTED WAS ADOLDED FOR STREET WAS ASSETTED FOR THE PROPERTY OF THE PARTY OF THE

TAKE OFF:

MONITOR "TAKEOFF THROTTLE SETTING" PROCEDURE MONITOR "PRECAUTIONARY ENG "1 SHUTDOWN" CHECKLIST MONITOR "FUEL JETTISON" CHECKLIST

AFTER TAKE OFF CLIMB:

MONITOR "HOBART FIVE DEPT 35" DEPARTURE PROFILE

APPROACH:

MONITOR "APPROACH" CHECKLIST
MONITOR "ALTUS LOW ILS RWY 35" APPROACH PROFILE

BEFORE LANDING:

MONITOR "BEFORE LANDING" CHECKLIST MONITOR "ALTUS ILS RWY 35" ILS-FINAL PROFILE MONITOR "ALTUS TACAN 17" APPROACH PROFILE MONITOR "BEFORE LANDING" CHECKLIST MONITOR "ALTUS VOR DME RWY 35" APPROACH PROFILE MONITOR "BEFORE LANDING" CHECKLIST

SESSION 2:

MONITORABLE PARAMETERS: STANDARD-LIST

BEFORE LANDING:

MONITOR "STANDARD FUEL MANAGEMENT" PROCEDURE MONITOR "HOBART FIVE DEPT 35" DEPARTURE PROFILE MONITOR "ALTUS LOW ILS RWY 35" APPROACH PROFILE MONITOR "BEFORE LANDING" CHECKLIST MONITOR "ALTUS ILS RWY 35" ILS-FINAL PROFILE MONITOR "ALTUS TACAN 17" APPROACH PROFILE MONITOR "BEFORE LANDING" CHECKLIST MONITOR "ALTUS VOR DME RWY 35" APPROACH PROFILE MONITOR "BEFORE LANDING" CHECKLIST MONITOR "LANDING" PROCEDURE

AFTER LANDING:

MONITOR "AFTER LANDING" CHECKLIST

ENGINE SHUTDOWN:

MONITOR "ENGINE SHUTDOWN" CHECKLIST

BEFORE LEAVING AIRCRAFT:

MONITOR "BEFORE LEAVING AIRPLANE" CHECKLIST

CREW MEMBER ASSESSMENT:

SESSION 1;	PILOT:		
CHECK-PROC		MIN	2
NAV PROFL		MIN	7

CHECK-PROC	WTN	<i>7</i> 6	70	CKIT	FACT	0.95	MCT	1.0
NAV PROFL	MIN	7	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER	MIN	%	70	CRIT	FACT	0.95	WGT	0.9

SESSION 1; COPILOT:

CHECK-PROC	MIN %	70	CRIT FACT	0.95	WGT 1.0
NAV PROFL	MIN %	70	CRIT FACT	0.95	WGT 1.0
PARAMETER	MIN %	70	CRIT FACT	0.95	WGT 0.9

SESSION 1; FLIGHT ENGINEER:

CHECK-PROC	MIN	%	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER	MIN	%	70	CRIT	FACT	0.95	WGT	0.7

SESSION 1; CREW CO	ORDIN	ልጥፕ	ON.					
CHECK-PROC	MTN	7	70	CRTT	FA CT	Λ 05	tion 1	Λ
NAV PROFI.	MTN	7	70	COLLI	PACT	0.75	WGI 1	.0
CHECK-PROC NAV PROFL PARAMETER	MTN	2	70	CRIT	FACT	0.95	MGI I	•0
		~	,,	OULL	PAGI	0.93	MGI U	• /
SESSION 2; PILOT:								
CHECK-PROC NAV PROFL PARAMETER	MIN	7	70	CRIT	FACT	0.95	WGT 1	٠.
NAV PROFL	MIN	7	70	CRIT	FACT	0.95	WGT 1	.0
PARAMETER	MIN	%	70	CRIT	FACT	0.95	WGT O	.9
								• /
SESSION 2; COPILOT:	:							
CHECK-PROC NAV PROFL PARAMETER	MIN	%	70	CRIT	FACT	0.95	WGT 1	.0
NAV PROFL	MIN	%	70	CRIT	FACT	0.95	WGT 1	.0
PARAMETER	MIN	%	70	CRIT	FACT	0.95	WGT O	.9
								•
SESSION 2; FLIGHT E	ing ini	EER	.:					
CHECK-PROC	MIN	7	70	CRIT	FACT	0.95	WGT 1	.0
CHECK-PROC PARAMETER	MIN	7	70	CRIT	FACT	0.95	WGT 0.	.7
								•
SESSION 2; CREW COO	RDINA	IT	ON:					
CHECK-PROC	MIN	7	70	CRIT	FACT	0.95	WGT 1.	0
NAV PROFL	MIN	7	70	CRIT			WGT 1.	
CHECK-PROC NAV PROFL PARAMETER	MIN	%	70	CRIT			WGT 0.	
SESSION ASSESSMENT:								
CHOCTON 1								
SESSION 1: PILOT COPILOT FLT ENGR		œ						
PILOT	MIN	7	70	CRIT			WGT 2.	
COPILOT FLT ENGR	MIN	7	70	CRIT			WGT 1.	
		~		O2(1 1			WGT 2.	
CREW COORD	MIN	76	70	CRIT	FACT	0.95	WGT 1.	5
SESSION 2:								
PILOT COPILOT	MTN	4	70	OD TO	T4.00	0 05	110m 0	_
COPILOT	MIN	6 4	70	CKII			WGT 2.	
	1.1714		70	OKII			WGT 1.	
CREW COORD	MIN	*	70 70			0.95		
OWNIA COOKT	WIM	^	/0	CRIT	FACT	U.Y5	WGT 1.)
MISSION ASSESSMENT:								
SESSION 1	MIN	Y	70	CRTT	ም ል ርጥ	0 05	WGT 1.	Λ
SESSION 2	MIN		70			0.95		
	*****	~	, 0	OUTI	ENUL	ひ・ブノ	MOT T.	v

APPENDIX C

AIRBORNE NOMINAL (NAVIGATIONAL PROFILE) MISSION OVERVIEW

MISSION: ? CREW: BOTH				
SESSION 1:				
SET-UP:				
AIRCRAFT CONFIGURATION:				
OPERATING-WEIGHT	333333	LBS		
RAMP-FUEL	333333	LBS		
CARGO/PAX	33333	LBS		
CENTER-OF-GRAVITY	??	%		
FUEL-MANAGEMENT	???			
TOLD CARD WORKSHEET:				
EPR-TRT-STAT	?.??			
EPR-TRT-IF	?.??			
EPR-T/O-STAT	?.??			
EPR-T/O-IF	?.??			
TAKE-OFF-STAB-TRIM	?.??			
V-ROT	???	KNOTS		
V-MCO	???	KNOTS		
V-MFR	???	KNOTS		
H-MFR	????	FEET		
V-TLS	???	KNOTS		
V-GO	???	KNOTS		
XWIND-T/O-MAX	?.?	DEG		
XWIND-T/O-MIN	?.?	DEG		
XWIND-SETTING-T/O	?.?	DEG		
XWIND-SETTING-LAND	?.?	DEG		
FLT-ALT-MAX	?????	FEET		
FLT-ALT-MIN	?????	FEET		
DEPARTURE INITIALIZATION:				
INITIAL-LATITUDE	34 38.64		; ALTUS 3	15
INITIAL-LONG ITUDE	99 16.52	W		
FIELD	ALTUS			
RUNWAY-IDENTIFIER	35			
RUNWAY-HEADING	351	DEG		
FIELD-ELEVATION	1378	FEET		
ALTIMETER-SETTING	??.??	IN HG		
RUNWAY-TEMPERATURE	?	DEG C		
CRUISE-TEMPERATURE-DEVIATION	?	DEG C		
WIND-DIRECTION	?	DEG		
WIND-VELOCITY	?	KNOTS		
WIND-GUSTS	333333			

MONITORABLE PARAMETERS:

AIRSPEED

ANGLE-OF-ATTACK

FLAP-POS-IND

GROUND-SPEED

L-LANDING-LIGHT-SW

LANDING-GEAR-LEVER

NLG-STEERING-IND

NOSE-LANDING-LIGHT-SW

PITCH

R-LANDING-LIGHT-SW

ROLL

VERT-ACCELEROMETER

VERTICAL-SPEED

YAW

AFTER TAKE OFF CLIMB:

MONITOR "HOBART FIVE DEPT 35" DEPARTURE PROFILE

APPROACH:

MONITOR "ALTUS LOW ILS RWY 35" APPROACH PROFILE

BEFORE LANDING:

MONITOR "ALTUS ILS RWY 35" ILS-FINAL PROFILE MONITOR "ALTUS TACAN 17" APPROACH PROFILE MONITOR "ALTUS VOR DME RWY 35" APPROACH PROFILE

SESSION 2:

MONITORABLE PARAMETERS:

AIRSPEED

ANGLE-OF-ATTACK

FLAP-POS-IND

GROUND-SPEED

L-LANDING-LIGHT-SW

LANDING-GEAR-LEVER

NLG-STEERING-IND

NOSE-LANDING-LIGHT-SW

PITCH

R-LANDING-LIGHT-SW

ROLL

VERT-ACCELER OME TER

VERTICAL-SPEED

YAW

BEFORE LANDING:

MONITOR "HOBART FIVE DEPT 35" DEPARTURE PROFILE MONITOR "ALTUS LOW ILS RWY 35" APPROACH PROFILE

MONITOR "ALTUS ILS RWY 35" ILS-FINAL PROFILE MONITOR "ALTUS TACAN 17" APPROACH PROFILE MONITOR "ALTUS VOR DME RWY 35" APPROACH PROFILE

CREW MEMBER ASSESSMENT:

SESSION 1;									
CHECK-PROC		MIN			CRIT	FACT	0.95	WGT	1.0
NAV PROFL		MIN			CRIT	FACT	0.95	WGT	1.0
CHECK-PROC NAV PROFL PARAMETER		MIN	%	70	CRIT	FACT	0.95	WGT	0.9
SESSION 1;	COPILOT:								
CHECK-PROC		MIN	%	70	CRIT	FACT	0.95	WGT	1.0
NAV PROFL		MIN	%	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER		MIN	%	70	CRIT	FACT	0.95	WGT	0.9
SESSION 1;	FLIGHT E	NG IN	EER	:					
CHECK-PROC		MIN	%	70	CRIT	FACT	0.95	WGT	1.0
CHECK-PROC PARAMETER		MIN	7	70	CRIT	FACT	0.95	WGT	0.7
SESSION 1;	CREW COO	RDIN	ATI	ON:					
CHECK-PROC		MIN	%	70	CRIT	FACT	0.95	WGT	1.0
NAV PROFL		MIN	%	70	CRIT				
CHECK-PROC NAV PROFL PARAMETER		MIN	%	70			0.95		
SESSION 2;	PILOT:								
CHECK-PROC		MIN	%	70	CRIT	FACT	0.95	WGT	1.0
NAV PROFL		MIN	%	70	CRIT	FACT	0.95	WGT	1.0
CHECK-PROC NAV PROFL PARAMETER		MIN	%	70	CRIT		0.95		
			••					,,,,,,	- • •
SESSION 2;	COPILOT:								
CHECK-PROC NAV PROFL		MIN	2	70	CRIT	FACT	0.95	WGT	1.0
NAV PROFL		MIN	Z	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER		MIN	7	70	CRIT	FACT	0.95	WGT	0.9
			••						
SESSION 2;	FLIGHT E	NG IN	EER	:					
					CRIT	FACT	0.95	WGT	1.0
CHECK-PROC PARAMETER		MIN	7	70	CRIT	FACT	0.95	WGT	0.7
				. •					- • •
SESSION 2;	CREW COOL	RDINA	ATI	ON:					
					CRIT	FACT	0.95	WGT	1.0
CHECK-PROC NAV PROFL		MIN	7	70	CRIT	FACT	0.95	WGT	1.0
PARAMETER		MIN	7	70	CRIT	FACT	0.95	WGT	0.7
		*****	e a		V41 4. 4	24701	U # 3" ef	****	~ • 1

SESSION ASSESSMENT:

SESSION 1: PILOT COPILOT FLT ENGR CREW COORD	MIN MIN MIN MIN	%	70 70 70 70	CRIT CRIT			ygt	2.0
SESSION 2: PILOT	MIN	*	70	CRIT	FACT	0.95	WGT	2.0
COPILOT	MIN		70		FACT		WGT	
FLT ENGR CREW COORD	MIN MIN	አ %	70 70		FACT FACT		WGT WGT	•

MISSION ASSESSMENT:

SESSION 1	MIN %	70	CRIT FACT 0.95	WGT 1.0
SESSION 2	MIN Z	70	CRIT FACT 0.95	WGT 1.0

APPENDIX D

CODE REFERENCE FOR APPENDIX E THROUGH APPENDIX H

CODE INDEX FOR VARIABLES REFERENCED BY MONITORABLE TASKS

NAVIGATIONAL PROFILES

D - INSTRUMENT DEPARTURE

E - ENROUTE

H - HOLDING PATTERN

A - INITIAL APPROACH

L - INSTRUMENT LANDING SYSTEM (ILS)

CHECKLISTS/PROCEDURES

ALL NORMAL ONES EXCEPT "AFTER TAKEOFF/CLIMB", "CRUISE", AND "DESCENT" "C:" FOLLOWED BY ORDINAL NUMBERS FROM CHECK.DY

MONITORABLE PARAMETERS

S: - STANDARD LIST

P: - OTHER

ORDINAL NUMBERS FROM PARAMETER.DY

VARIABLE DATA TYPES (FOLLOWING VARIABLE NAME)

1 - BOOLEAN

2 - HALF BYTE (16 VALUES OR FEWER)

3 - FULL WORD INTEGER

4 - REAL (FLOATING POINT)

5 - DOUBLE PRECISION INTEGER

MADAR SAR LOCATIONS (FOLLOWING DATA TYPE)

L<SS>/<CC>[C][F][*]

WHERE

L = "A" FOR AUTOMATIC, OR "M" FOR MANUAL

<SS> = 2-DIGIT SAR NUMBER

<CC> = 2-DIGIT CHANNEL NUMBER

C = CDPIR PARAMETER

F = FLRS PARAMETER

* = QUESTIONABLE SOURCE

OTHER SOURCE CODES

INS = INERTIAL NAVIGATION SYSTEM FDC- = FLIGHT DIRECTOR COMPUTER

SAME = SAME SOURCE AS VARIABLE INDICATED IN COMMENT

FLYFR = COMPUTED BASED ON WHO IS FLYING

APPENDIX E

SIGNALS REQUIRED FOR AIRBORNE MONITORING

	DATA [YP]						FILE, ENCES	CH	ECKL	ist/1	PROCE	DURE	,
25-L-OXYGEN-QTY-IND	3		C:		s:	01							
25-L-OXYGEN-QTY-LOW-LT	1		C:										
25-L-OXYGEN-QTY-TEST-ST			C:		_								
75-L-OXYGEN-QTY-IND	3		C:		s:	02							
75-L-OXYGEN-QTY-LOW-LT	1		C:	57									
75-L-OXYGEN-QTY-TEST-SV			C:										
A-MLG-SPIN-TEST-SW	2		C:										
A-PITCH-TRIM-GROUND-SW			C:										
A-PITCH-TRIM-POWER-SW	2		C:										
A-TRIM-TEST-SW	2		C:	61									
A/C-WEIGHT	4		C:	13,	21								
A/P-ALT-HOLD-SW	1		C:	62									
A/P-DISC-SW	1		C:										
A/P-PITCH-OFF-LT	1		C:										
A/P-PITCH-WHEEL	3		C:										
A/P-ROLL-OFF-LT	1		C:										
A/P-TURN	3		C:										
AC-FREQUENCY-METER	3		S:										
AC-VOLTME TER	3		s:										
ADF-REL-BEARING	3	FLYER	H										
ADF1-FREQUENCY	3		DEH										
ADF1-FUNC-SW	2		DEH										
ADF1-REL-BEARING	3		H										
ADF2-FREQUENCY	3		DEH										
ADF2-FUNC-SW	2		DEH										
ADF2-REL-BEARING	3		H										
AERIAL-REF-BOOM-LATCH-	SWI		C:	57									
AERIAL-REFUEL-DOORS-SW	1		C:	57									
AERIAL-REFUEL-ELEC-PWR	1		C:										
AFCS-RESET/FAIL-BUTTON	1		C:	62									
AFCS-TEST-LT	1		C:	62									
AIR-CONDITIONING-SW	2	A01/14	C:	19,	25,	57,	92						
AIRFLOW-SW	2		C:	57									
AIRSPEED	3		C:	14,	64	S:	05,	47,	57,	69,	75		
ALDCS-SW	1	A14/10	C:	04,	24,	62							
ALTITUDE	4	A06/30F	DEH				02, 0	5,	57				
ALTITUDE-AGL	3		C:		64,								
			s:				47, 7	1,	75				
ANGLE-OF-ATTACK	3		s:	06									
APU-GEN-SELECT-SW	2		C:	03,	12,	19,	21, 5	6,	92	S:	03,	04	

```
MONVAR VARIABLE
                         DATA
                                 SAR
                                         NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                         TYPE
                                         PARAMETER REFERENCES
 APU/EXT-POWER-SW
                                             03, 12, 19, 21, 56, 92
                                                                            04
                                                                        S:
                                         P:
                                             46
 AUTO-REFUEL-SW
                           1
                                         C:
                                             09, 44
 AVIONICS-FAN-SW
                           1
                                         C:
                                             57
 AVIONICS-ZONE-WARN
                           1
                                         C:
                                             59
 BAILOUT-ALARM-SW
                           1
                                         C:
                                             63
 BANK
                           3
                             INS
                                         DE
 BATTERY-SELECT-SW
                           2
                                         C:
                                             12, 21
 BRAKE-PRES-NORM
                           3
                                         C:
                                             12
 BRAKE-SUPPLY-SELECT-SW
                                             12, 14, 22, 26, 45, 60, 63
                                         C:
 BRAKES-LT
                           1
                                         C:
                                             20, 22, 45, 60, 63
 BUS-TIE1-OPEN-LT
                           1
                                         C:
                                             92
 BUS-TIE2-OPEN-LT
                           1
                                        C:
                                             92
 BUS-TIE3-OPEN-LT
                           1
                                         C:
                                             92
 BUS-TIE4-OPEN-LT
                           1
                                        C:
                                             92
 C-ALTITUDE
                            SAME
                                        DEHA
                                                ; AS ALTITUDE
 C-CADC-SW
                           2
                                        C: 63
 C-CDI
                           4 FDC2
                                        DEHAL
 C-CDI-WARNING
                           1 FDC2
                                        DEHAL
 C-COURSE-SET
                                        DEH
C-DUCT-OVERHEAT-LT
                          1
                                        C:
                                            57
 C-G/S-DEVIATION-IND
                          4 FDC2
                                             L
C-G/S-DEVIATION-WARN
                          1 FDC2
                                            L
C-NAV-SELECT
                          2 FDC2
                                        DEKAL
C-PITOT-HEAT-SW
                          1
                                        C: 04, 12, 63, 68
C-RADAR-ALT-SW
                          1
                                        C: 22
C-RATE-OF-TURN
                            SAME
                                           AL
                                                 ; AS RATE-OF-TURN
C-ROLL-HUB-FORCE
                          3
                                        DEHAL
                                                 C:
                                                    62
C-SEPARATION-SW
                          1
                                        C:
                                            44, 58
CABIN-FLIGHT-ALT
                          3
                                        S:
                                            07
CABIN-PRES-DIFFERENCE
                          4
                                        C:
                                            03
                                                 S: 08
CABIN-PRES-MODE-SW
                          2
                                        C:
                                            23, 57, 95
CABIN-ROC-CON
                          3
                                        C;
                                            57
CARGO-SW
                          2 A03/28
                                        C:
                                            57
CDI
                          4 FLYER
                                        DEHAL
CDI-WARNING
                          1 FLYER
                                        DEHAL
CMA-MESSAGE
                          5
                                            13, 21
                                        C:
COLUMN-POS-CMD
                                        C:
                                            61
CONTINUOUS-IGNITION
                          1
                                        C:
                                            12, 45, 93
COURSE-SET
                          3 FLYER
                                        DEH
CSD1-DISCONNECT-SW
                          1
                                        C:
                                            12, 92
                                                     S:
                                                         03, 09
CSD1-FAIL-LT
                          1
                                        C:
                                            92
CSD1-OIL-TEMP
                          3
                                        S:
                                            09
CSD2-DISCONNECT-SW
                          1
                                            12, 92
                                        C:
                                                     S:
                                                          03, 10
CSD2-FAIL-LT
                          1
                                       C:
                                            92
CSD2-OIL-TEMP
                          3
                                       S:
                                            10
CSD3-DISCONNECT-SW
                                       C:
                                            12, 92
                                                         03, 11
CSD3-FAIL-LT
                         1
                                       C:
                                            92
CSD3-CIL-TEMP
                         3
                                       S:
                                            11
```

```
NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                               SAR
  MONVAR VARIABLE
                        DATA
                                        PARAMETER REFERENCES
                        TYPE
                                                      S:
                                                           03, 12
                                            12, 92
CSD4-DISCONNECT-SW
                          1
                                        C:
                                            92
                          1
CSD4-FAIL-LT
                                            12
                                        S:
                          3
CSD4-01L-TEMP
                                        S:
                                             13
DC-VOLTMETER
                                             12
                                                      13
                                                  S:
                          2
                                        C:
DCVM-SELECT-SW
                                        C:
                                             12
ELEV-FEEL-SYS1-SW
                          1
                                        C:
                                             12
ELEV-FEEL-SYS4-SW
                                        C:
                                             57
EMER-DEPRESS-SW
                          1
                                             56
                                        C:
ENG-&-APU-FIRE-DET-SW
                                             10, 25, 44, 57, 92
                          2 A04/20
                                        C:
ENG1-A/I-SW
                                        C:
                                             44, 57, 92
                          1
ENG1-AUG-AIR-SW
                                             57, 92
                                                       S:
                                                           54
                          1 A04/16
                                        C:
ENGI-BLEED-AIR-SW
                                             94
                                                  S:
                                                      14
                            A19/30C
                                        C:
ENG1-EPR
                                             59
                          1
                                        C:
ENG1-FIRE-HANDLE
                                                               19
                                                                         20
                                                                     P:
                                             12, 45, 93
                                                           S:
                                        C:
ENG1-FUEL-&-START-IGN
                          3 A03/22C
                                         S:
                                             15
ENG1-FUEL-FLOW
                                        C:
                                             58
                          1 A04/15
ENG1-FUEL-HEATER-SW
                                             93
                                         C:
ENG1-LOW-OIL-PRES-LT
                           1
                                             16
                           3 A04/14C
                                        P:
ENG1-N1-RPM
                                                           04, 17, 18, 76
                                             92, 93
                                                       S:
                            A04/09C
                                         C:
ENG1-N2-RPM
                                         s:
                                             18
                           3 A03/07C
ENG1-OIL-PRESSURE
                                             18, 19
                           3 A19/04
                                         S:
ENG1-OIL-TEMP
                                                       15
                                                   S:
                                             93
                                         C:
ENG1-START-BUTTON
                           1
                                              20
                                         P:
                           1
ENG1-START-CYCLE
                                             92, 93
ENG1-START-VALVE-OPEN-LT1
                                         C:
                                         C:
                                              94
                                                   S:
                                                      15, 21
                           3 A04/29C
ENG1-TIT
                                              10, 25, 44, 57, 92
                                         C:
                             A04/21
ENG2-A/I-SW
                                              44, 57, 92
                                         C:
                           1
ENG 2-AUG-AIR-SW
                                              57, 92
                                                            54
                                         C:
                                                       S:
                             A04/17
ENG2-BLEED-AIR-SW
                                              59
                           î
                                         C:
ENG2-FIRE-HANDLE
                                                                          28
                                                                      P:
                                                                25
                                                            S:
                                         C:
                                              12, 45, 93
ENG2-FUEL-&-START-IGN
                           2
                                              22
                           3 A03/18C
                                         S:
ENG2-FUEL-FLOW
                                              58
                                         C:
                           1 A04/11
ENG2-FUEL-HEATER-SW
                                              93
                           1
                                         C:
 ENG 2-LOW-OIL-PRES-LT
                                                            04, 23, 24, 77
                                         C:
                                              92, 93
                           3
                             A04/02C
 ENG2-N2-RPM
                                              24
                           3
                             A03/03C
                                         S:
 ENG2-OIL-PRESSURE
                                              24, 25
                                         S:
                           3 A20/04
 ENG2-OIL-TEMP
                                         C:
                                              94
                                                        26
                           4 A20/30C
 ENG2-P-EPR
                           3 A04/13C
                                         P:
                                              27
 ENG2-P-N1-RPM
 ENG2-REV-TH-EMER-RET-SW
                                         C:
                                              59
                           1
                                                        22
                                              93
                                                   S:
                                         C:
                           1
 ENG2-START-BUTTON
                                              28
                                         P:
                           1
 ENG2-START-CYCLE
                                              92, 93
 ENG2-START-VALVE-OPEN-LT1
                                         C:
                                                   S:
                                                        22, 29
                                              94
                           3 A04/25C
                                         C:
 ENG 2-TIT
                                              10, 25, 44, 57, 92
                                         C:
                             A04/22
 ENG3-A/I-SW
                                         C:
                                              44, 57,
                                                      92
                           1
 ENG3-AUG-AIR-SW
                                              57, 92
                                                        S:
                                                            73
                                         C:
                           1 A04/18
 ENG3-BLEED-AIR-SW
                                                   S:
                                                        30
                                              94
                                         C:
                           4 A21/30C
 ENG3-EPR
                                                        04, 33
                                                   S:
                           3 A04/06C
                                         C:
                                              92
 ENG3-F-N2-RPM
```

```
MONVAR VARIABLE
                        DATA
                                SAR
                                         NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                         TYPE
                                         PARAMETER REFERENCES
 ENG3-FIRE-HANDLE
                           1
                                             59
                                         C:
 ENG3-FUEL-&-START-IGN
                           2
                                         C:
                                             12, 45, 93
                                                               34
                                                                    P:
                                                                        36
 ENG3-FUEL-FLOW
                           3 A03/26C
                                         S:
                                             31
 ENG3-FUEL-HEATER-SW
                          1 A04/07
                                         C:
                                             58
 ENG3-LOW-OIL-PRES-LT
                          1
                                         C:
                                             93
ENG3-N1-RPM
                          3 A04/01C
                                             32
                                        P:
 ENG3-OIL-PRESSURE
                          3 A03/05C
                                        S:
ENG3-OIL-TEMP
                          3 A21/04
                                        S:
                                            33, 34
ENG3-P-N2-RPM
                          3 A04/06C
                                        C:
                                             93
                                                  S:
                                                      35, 78
ENG3-REV-TH-EMER-RET-SW 1
                                        C:
                                             59
ENG3-START-BUTTON
                          1
                                        C:
                                             93
                                                      31
ENG3-START-CYCLE
                          1
                                        P:
                                             36
ENG3-START-VALVE-OPEN-LT1
                                             92, 93
                                        C:
ENG3-TIT
                          3 A04/26C
                                        C:
                                             94
                                                  S: 31, 37
ENG4-A/I-SW
                          1 A04/23
                                        C:
                                             10, 25, 44, 57, 92
ENG4-AUG-AIR-SW
                                        C:
                                             44, 57, 92
ENG4-BLEED-AIR-SW
                          1 A04/19
                                             57, 92
                                        C:
                                                      S:
                                                          73
ENG4-EPR
                          4 A22/30C
                                        C:
                                             94
                                                  S: 38
ENG4-F-N2-RPM
                          3 A04/05C
                                        C:
                                             92
                                                  S: 04, 39
ENG4-FIRE-HANDLE
                          1
                                        C:
                                             59
ENG4-FUEL-&-START-IGN
                          2
                                        C:
                                            12, 45, 93
                                                              40
ENG4-FUEL-HEATER-SW
                          1 A04/03
                                        C:
                                            58
ENG4-LOW-OIL-PRES-LT
                          1
                                            93
                                        C:
ENG4-OIL-PRESSURE
                          3 A03/01C
                                        S:
                                            39
ENG4-OIL-TEMP
                          3 A22/04
                                            39, 40
                                        S:
ENG4-P-FUEL-FLOW
                          3 A03/30C
                                        S:
                                            41
ENG4-P-N1-RPM
                          3 A04/10C
                                        P:
                                            42
ENG4-P-N2-RPM
                          3 A04/05C
                                        C:
                                            93
                                                      43, 79
                                                 S:
ENG4-P-TIT
                          3 A04/30C
                                        C:
                                            94
                                                 S:
                                                      41, 44
ENG4-START-BUTTON
                                        C:
                                            93
                                                      41
ENG4-START-CYCLE
                          1
                                        P:
                                            45
ENG4-START-VALVE-OPEN-LT1
                                        C:
                                            92, 93
ENGINE-1-RUNNING
                          1
                                        C:
                                            10, 91
                                                      S:
                                                          03, 09, 14, 15, 17, 18
                                            16, 20
ENGINE-2-RUNNING
                          1
                                        C:
                                            10
                                                 S:
                                                     03, 10, 22, 23, 24, 26
                                            27, 28
ENGINE-3-RUNNING
                          1
                                            10
                                        C:
                                                 S:
                                                     03, 11, 30, 31, 33, 35
                                        P:
                                            32, 36
ENGINE-4-RUNNING
                                        C:
                                            10
                                                 S: 03, 12, 38, 39, 41, 43
                                        P:
                                            42, 45
EXT-ELECTRIC-POWER
                                            19, 21, 56
                          1
                                        C:
                                                          P:
EXT-POWER-LOADMETER
                                        P:
                                            46
EXT-POWER-LT
                          1
                                            12
                                       C:
F-MLG-SPIN-TEST-SW
                                        C:
                                            63
FILL-MAIN1-SW
                          1
                                            09, 44, 91
                                       C:
FILL-MAIN2-SW
                                        C:
                                            09, 44, 91
FILL-MAIN3-SW
                                            09, 44, 91
                          1
                                       C:
FILL-MAIN4-SW
                          1
                                       C:
                                            09, 44, 91
FLAP-HANDLE
                          3
                                       C:
                                            04, 14, 61
                                                              05
```

```
MONVAR VARIABLE
                       DATA
                              SAR
                                       NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                       TYPE
                                       PARAMETER REFERENCES
FLAP-POS-IND
                         3 A18/29CF
                                           14, 22, 24, 26, 60, 68, 94
                                           05, 14, 26, 30, 38, 47 P:
                                       S:
FLIGHT-L-SYS-A-SW
                         1
                                       C:
                                           12
FLIGHT-L-SYS-B-SW
                         1
                                       C:
                                           12
                         1
                                       C:
                                           12
FLIGHT-R-SYS-A-SW
                                           12
FLIGHT-R-SYS-B-SW
                         1
                                       C:
                         2 A03/16
                                       C:
                                           57
FLIGHT-STA-SW
                         2 A01/09
                                       S:
                                           09, 21, 44, 57, 59
FLOOR-HEAT-SW
FSS-ARM-SW
                         1
                                       C:
                                           59
FUEL-DIF-MAINS-1&2
                         4
                                       C:
                                           09
FUEL-DIF-MAINS-3&4
                                       C:
                                           09
FUEL-ISO-VALVE-1-SW
                                       C:
                                           44, 58
                                           44, 58
FUEL-ISO-VALVE-2-SW
                                       C:
FUEL-ISO-VALVE-3-SW
                         1
                                       C:
                                           44, 58
                         1
                                           44, 58
FUEL-ISO-VALVE-4-SW
                                       C:
                                           58
FUEL-QTY-IND-EXRG1
                                       C:
                                           58
FUEL-QTY-IND-EXRG2
                                       C:
FUEL-QTY-IND-EXRG3
                                       C:
                                           58
FUEL-QTY-IND-EXRG4
                                           58
                                       C:
FUEL-QTY-TEST-AUX1
                                       C;
                                           58
FUEL-QTY-TEST-AUX2
                                           58
                                       C:
                         1
FUEL-QTY-TEST-AUX3
                                       C:
                                           58
                                           58
FUEL-QTY-TEST-AUX4
                         1
                                       C:
                                           58
FUEL-QTY-TEST-EXRG1
                         1
                                       C:
FUEL-QTY-TEST-EXRG2
                                       C:
                                           58
                                       C:
                                           58
FUEL-QTY-TEST-EXRG3
                         1
FUEL-QTY-TEST-EXRG4
                         1
                                       C:
                                           58
FUEL-QTY-TEST-MAIN1
                         1
                                       C:
                                           58
FUEL-QTY-TEST-MAIN2
                         1
                                       C:
                                           58
FUEL-QTY-TEST-MAIN3
                                       C:
                                           58
FUEL-QTY-TEST-MAIN4
                         1
                                       C:
                                           58
                         2
                                           23
FUEL-TEMP-SELECT-SW
                                       C:
                         2 MO1/03
GEN-VOLTS-&-FREQ-SW
                                           03, 21, 56, 92
                                                             S:
                                                                 03, 04
                                       C:
GEN1-BUS-TIE-SW
                                       C:
                                           03, 12
                                                   P: 80
GEN1-LOADMETER
                                       P:
                                           48
GEN1-OUT-LT
                         1
                                           92
                                       C:
GEN1-SW
                         2
                                           03, 12
                                                         03,04
                                       C:
                                                    S:
                                                                  P:
GEN2-BUS-TIE-SW
                         2
                                           03, 12
                                       C:
GEN2-LOADMETER
                                           49
                                      C:
GEN2-OUT-LT
                         1
                                           92
                                                P:
                                                    49
                                           03, 12
GEN2-SW
                                       C:
                                                    S:
                                                         03, 04
                         2
GEN3-BUS-TIE-SW
                                       C:
                                           03, 12
                         4
                                       P:
                                           50
GEN3-LOADMETER
                         1
GEN3-OUT-LT
                                       C:
                                           92
                         2
GEN3-SW
                                       C:
                                           03, 12
                                                    S:
                                                         03,04
                                                                  P:
                                                                      50
GEN4-BUS-TIE-SW
                         2
                                       P:
                                           81
                         4
GEN4-LOADMETER
                                      P:
                                           51
                         1
GEN4-OUT-LT
                                      C:
                                           92
GEN4-SW
                                           03, 12
                                                         03, 04
                                                    S:
```

```
MONVAR VARIABLE
                        DATA
                                SAR
                                        NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                        TYPE
                                        PARAMETER REFERENCES
GROUND-L-SYS-A-SW
                                            12
                          1
                                        C:
GROUND-L-SYS-B-SW
                          1
                                        C:
                                            12
GROUND-R-SYS-A-SW
                          1
                                        C:
                                            12
GROUND-R-SYS-B-SW
                          1
                                        C:
                                             12
GROUND-SPEED
                          3 INS?
                                        S:
                                            63, 64, 65, 66, 68
                                                                   P:
                                                                      52
GROUND-SPOILER-HANDLE
                          3 A08/01F*
                                        C:
                                            04, 12, 24, 61, 64
                          4 FLYER
                                            L
GSI-WARNING
                          1 FLYER
                                            L
HORN-SW
                                            59
                                        C:
I-FUEL-PUMP-AUX1
                          1
                                        C:
                                            03, 58, 91
I-FUEL-PUMP-AUX2
                                            03, 58, 91
                                        C:
I-FUEL-PUMP-AUX3
                          1
                                        C:
                                            03, 58, 91
I-FUEL-PUMP-AUX4
                          1
                                        C:
                                            03, 58, 91
I-FUEL-PUMP-EXRG1
                                        C:
                                            03, 09, 58, 91
I-FUEL-PUMP-EXRG2
                          1
                                            03, 09, 58, 91
                                        C:
I-FUEL-PUMP-EXRG3
                                        C:
                                            03, 09, 58, 91
I-FUEL-PUMP-EXRG4
                                            03, 09, 58, 91
I-FUEL-PUMP-MAIN1
                                        C:
                                            03, 09, 58, 63, 91
I-FUEL-PUMP-MAIN2
                                            03, 09, 58, 63, 91
                                        C:
I-FUEL-PUMP-MAIN3
                                            03, 09, 58, 63, 91
                                        C:
I-FUEL-PUMP-MAIN4
                          1
                                            03, 09, 58, 63, 91
                                        C:
ICE-ARMED-SW
                                            10, 25, 92
                          1
                                        C:
ICE-DETECT-TEST-SW
                                        C:
                                            25
ICE-DETECTOR-SW
                          2
                                            10, 25, 26, 44
                                        C:
                          2
INS1-MSU-MODE-SW
                                        C:
                                            45, 59
INS1/3-ROLL
                          3
                            SAME
                                        DE
                                                    ; AS BANK
INS2-MSU-MODE-SW
                          2
                                            45, 59
INS2/3-ROLL
                          3 SAME
                                        DE
                                                    ; AS BANK
INS3-MSU-MODE-SW
                          2
                                        C:
                                            45, 59
INSTRUMENT-POWER-SW
                          2
                                            12, 45
                                        C:
ISO-BUS-SW
                                        C:
                          1
                                            12
KEYSET
                          5
                                        C:
                                            44, 63
KNEEL-COMMAND-SW
                          2
                                        C:
                                            57
KNEEL-SELECT-SW
                                            57
                                        C:
L-AERIAL-REFUEL-SW
                                            57
                          1
                                        C:
L-AIL-SYS1-SW
                                            12, 62
                                        C:
L-AIL-SYS2-SW
                          1
                                        C:
                                            12, 62
L-AIL-TRIM-IND
                                        C.
                                            24, 61
L-AOA-VANE-HEATER-SW
                          1
                                       C:
                                            04, 12, 63, 68
L-CROSSFEED-SW
                          1
                                        C:
                                            03, 09, 44, 58, 91
L-DUCT-OVERHEAT-LT
                          1
                                        S:
                                            54
L-DUCT-OVERHEAT-SW
                          2
                                        C:
                                            57
                            A05/04
L-FLOW-CONTROL-SW
                          1
                                       C:
                                            57
L-FUEL-JETT-SW
                          1
                                            58
                                        C:
L-GROUND-REFUEL-SW
                                        C:
                                            58
L-I-ELEV-SYS2-SW
                                            12, 61, 62
                          1
                                        C:
L-I-ELEV-SYS3-SW
                                            12, 22, 59, 61, 62
                          1
L-I-WING-DIS-SW
                          1
                                        C:
                                            59
L-LANDING-LIGHT-SW
                                            09, 11, 60, 68, 91
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MONVAR VARIABLE
                       DATA
                              SAR
                                      NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                       TYPE
                                      PARAMETER REFERENCES
                         1
                                           59
L-MAIN-WW-DIS-SW
                                      C:
                         3 A07/17,25
L-MAN I FOLD-PRESSURE
                                      S:
                                           54
L-O-WING-DIS-SW
                         1
                                      C:
                                          59
L-PTU-DIS-SW
                                           59
                                      C:
                         2
                                      C:
                                         12
L-RATIO-SHIFTER-SW
L-RUDDER-SYS2-SW
                                      C:
                                          12, 62
                         1
L-RUDDER-SYS3-SW
                                      C:
                                          12, 62
L-SEPARATION-SW
                                      C:
                                           09, 44, 58, 91
L-WING-ISO-SW
                         1
                                      C:
                                           57
                         1
                                           59
L-WING-VENT-OPEN
                                      C:
L-WING-VENT-SW
                         1
                                      C:
                                           59
                         1 A01/03
LANDING-GEAR-LEVER
                                      C:
                                           10, 11, 12, 13, 14, 94
                                      P:
                                           59, 60, 61, 62, 67
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LAPU-BLEED-AIR-SW
                         1
                                                                    S:
                                                                         54, 73
                                      C:
                                           03, 19, 21, 25, 56 S: 56
LAPU-CONT-SW
                                      C:
LAPU-DOOR-OPEN-LT
                         1
                                      C:
                                           21, 56
LAPU-EGT-IND
                         3 A03/02
                                      S:
                                           56
LAPU-FIRE-HANDLE
                                      C:
                                           56
                                           03, 23, 57
LAPU-ISO-SW
                         1
                                      C:
LAPU-ISO-VALVE-OPEN-LT
                        1
                                      C:
                                           57
                         1
                                           03, 21
LAPU-ON-SPEED-LT
                                      C:
                                                    S:
                                                        03, 04, 56
LAPU-START-LT
                                      C:
                                           21, 56
                                          62
                         1
                                      C:
LATERAL-AUG-OFF-LT
LATERAL-AUG-SW
                         1 A17/07
                                      C: 22, 26, 45
                         5 INS
                                      DEHAL
LATITUDE
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                         5 INS
                                      DEHAL
MACH
                         4 A05/30F
                                      S: 05, 57
MADAR-OPERATE
                         1
                                      C:
                                           21
MADAR-POWER
                         1
                                           21
                                      C:
                                       EHAL
                                                   58
MAG-HEADING
                                               S:
MAIN-BUS1-AFT-OFF-LT
                                      C:
                                           56
MAIN-BUS1-FWD-OFF-LT
                         1
                                      C:
                                           56
MAIN-BUS2-AFT-OFF-LT
                         1
                                      C:
                                           56
MAIN-BUS2-FWD-OFF-LT
                         1
                                      C:
                                           56
MAIN-BUS3-AFT-OFF-LT
                                      C:
                                           56
MAIN-BUS3-FWD-OFF-LT
                                      C:
                                           56
MAIN-BUS4-AFT-OFF-LT
                         1
                                      C:
                                           56
MAIN-BUS4-FWD-OFF-LT
                         1
                                      C:
                                           56
MAIN1-SUMP-LOW-TEST-SW
                         2
                                           58
                                      C:
                                           58
MAIN4-SUMP-LOW-TEST-SW
                                      C:
MANUAL-CABIN-PRES
                                      C:
                                           57
MASTER-POWER-ON-LATERAL 1
                                      C:
                                           20, 62
MASTER-POWER-ON-PITCH
                         1
                                      C:
                                           62
                         1
                                      C:
                                           59, 68
MLG-CASTER-SW
MLG-EMER-EXT-L-A
                         1
                                      P:
                                           59
                         1
                                      P:
                                          60
MLG-EMER-EXT-L-F
MLG-EMER-EXT-R-A
                         1
                                      P:
                                           61
MLG-EMER-EXT-R-F
                         1
                                      P:
                                           62
                                      S:
                                           05
                                                P:
                                                    59
MLG-IND-L-A
```

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MONVAR VARIABLE
                       DATA
                               SAR
                                       NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                       TYPE
                                       PARAMETER REFERENCES
                                           60
MLG-IND-L-F
                         2
                                       P:
                         2
                                       P:
                                           61
MLG-IND-R-A
                         2
MLG-IND-R-F
                                       P:
                                           62
MLG-ON-GROUND
                                           64
MLG-POS-IND-L-A
                                       C:
                                           68
                                                S:
                                                   63
                                                    64
MLG-POS-IND-L-F
                                           68
                                           68
MLG-POS-IND-R-A
                                       C:
                                                S:
                                                    65
                                           68
                                                S:
MLG-POS-IND-R-F
                                       C:
                                                    66
MON-BUS2-OVRD-SW
                                       C:
                                           03, 12, 21, 56, 92
                                       C:
MON-BUS3-OVRD-SW
                                           03, 12, 21, 56, 92
NFS-TEST-SW
                                       C:
                                           59
NLG-EMER-EXT-SW
                                       P:
                                           67
NLG-IND
                                       S:
                                           05, 57
                                                     P:
                                                         67
                                       C;
NLG-ON-GROUND
                         1
                                           64
                                           68
                                                    68
NLG-POS-XWIND-IND
                                       C:
                                                S:
NLG-STEERING-IND
                                           69
                                       S:
                                           59
NLG-STEER ING-SW
                                       C:
NOSE-LANDING-LIGHT-SW
                                           11, 60, 68
                                       C:
                                                         P:
                                                             70
                                           59
NOSE-WHEEL-WELL-DIS-SW
                                       C:
O-ELEV-SYS1-SW
                                       C:
                                           12
                                       C:
                                           12
O-ELEV-SYS2-SW
                                           12
O-ELEV-SYS3-SW
                                       C:
                                           03, 09, 58, 91
O-FUEL-PUMP-AUX1
                                       C:
                                           03, 09, 58, 91
O-FUEL-PUMP-AUX2
O-FUEL-PUMP-AUX3
                                           03, 09, 58, 91
O-FUEL-PUMP-AUX4
                                           03, 09, 58, 91
                                       C:
                                           03, 09, 58, 91
O-FUEL-PUMP-EXRG1
                                       C:
                                           03, 09, 58, 91
O-FUEL-PUMP-EXRG2
                                       C:
O-FUEL-PUMP-EXRG3
                                           03, 09, 58, 91
O-FUEL-PUMP-EXRG4
                                       C:
                                           03, 09, 58, 91
                                           03, 09, 58, 63,
O-FUEL-PUMP-MAINI
O-FUEL-PUMP-MAIN2
                                           03, 09, 58, 63, 91
                                           03, 09, 58, 63, 91
O-FUEL-PUMP-MAIN3
O-FUEL-PUMP-MAIN4
                                           03, 09, 58, 63, 91
                                       DL C: 03, 04, 09, 64, 91, 94
ON-GROUND
                         1 A15/27
                                       S: 05, 06, 14, 26, 30, 38, 47, 55, 56,
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                                           52, 82, 83, 84
P-ALTITUDE
                         4 SAME
                                       DEHA
                                                ; AS ALTITUDE
                         2
P-CADC-SW
                                       C: 62
P-CDI
                         4 FDC1
                                       DEHAL
P-CDI-WARNING
                         1 FDC1
                                       DEHAL
P-COURSE-SET
P-G/S-DEVIATION-IND
                         4 FDC1
                                           L
P-G/S-DEVIATION-WARN
                         1 FDC1
                                           L
P-NAV-SELECT
                         2 FDC1
                                       DEHAL
                                       C: 04, 12, 63, 68
P-PITOT-HEAT-SW
                         1
P-RADAR-ALT-SW
                         1
                                       C: 09, 22, 63, 91
                                          AL ; AS RATE-OF-TURN
P-RATE-OF-TURN
                         4 SAME
```

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NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
   MONVAR VARIABLE
                       DATA
                              SAR
                       TYPE
                                       PARAMETER REFERENCES
P-ROLL-HUB-FORCE
                                       DEHAL
                                               C: 61
                                           12, 20, 61
PACS-PITCH-SW
                         1
                                       C:
                                          12, 20, 61
PACS-ROLL-SW
                         1
                                       C:
PHASE-SELECT-SW
                                       C:
                                           03, 56
                         3 FDC
                                       S:
                                          71
PITCH
PITCH-AUG-OFF-LT
                         1
                                       C:
                                           62
                         1 A17/27
                                           22, 26, 45
PITCH-AUG-SW
                                       C:
                                               C: 62
PITCH-C-HUB-FORCE
                         3
                                       DEHAL
                         3
                                      DEHAL
                                               C:
PITCH-P-HUB-FORCE
PITCH-TRIM-GROUND-SW
                         2
                                       C:
                                           61, 62
PITCH-TRIM-IND
                                           24, 61
                                       C:
                                           61
PITCH-TRIM-MANUAL-LEVER
                         3
PITCH-TRIM-MANUAL-SW
                         1
                                       C:
                                           61
PITCH-TRIM-POWER-SW
                         2
                                       C:
                                           61, 62
PRE-CHECK-SW
                         2
                                      C:
                                           58
PTU-1/2-SW
                         1
                                           10, 11, 25, 44, 59, 63, 92
                                                                             77
                                       C:
PTU-2/3-SW
                                           44, 59, 63, 92 S: 77, 78
                         1
                                       C:
                                           10, 11, 25, 44, 59, 63
PTU-3/4-SW
                         1
                                       C:
                                                                         78
                                      C:
R-AERIAL-REFUEL-SW
                         1
                                           57
R-AIL-SYS2-SW
                                       C:
                                           12, 62
                         1
                                       C:
                                          12, 62
R-AIL-SYS4-SW
                                           24, 61
R-AIL-TRIM-IND
                         4
                                       C:
R-CROSSFEED-SW
                         1
                                       C:
                                           03, 09, 44, 58, 91
R-DUCT-OVERHEAT-LT
                         1
                                       S:
                                           73
R-DUCT-OVERHEAT-SW
                                      C:
                                           57
                                           57
R-FLOW-CONTROL-SW
                         1 A10/30
                                       C:
                                           58
R-FUEL-JETT-SW
                                       C:
                                           58
R-GROUND-REFUEL-SW
                         2
                                       C:
R-I-ELEV-SYS2-SW
                                       C:
                                           12, 22, 59, 61, 62
R-I-ELEV-SYS3-SW
                                       C:
                                           12, 61, 62
                                       C:
                                           59
R-I-WING-DIS-SW
                         1
                                           09, 11, 60, 68, 91
R-LANDING-LIGHT-SW
                                       C:
                                                                P: 72
                                           59
R-MAIN-WW-DIS-SW
                         1
                                       C:
R-MANIFOLD-PRESSURE
                         3 \text{ A07/10,14}
                                      S:
                                          73
R-O-WING-DIS-SW
                         1
                                       C:
                                           59
R-PTU-DIS-SW
                         1
                                       C:
                                           59
                         2
R-RATIO-SHIFTER-SW
                                       C:
                                           12
                                       C:
                                           09, 44, 58, 91
R-SEPARATION-SW
                         1
                                           57
R-WING-ISO-SW
                                      C:
R-WING-VENT-OPEN
                                       C:
                                           59
                                       C:
                                           59
R-WING-VENT-SW
                         1
RAPU-BLEED-AIR-SW
                                           03, 19, 21 56, 57, 92 *
                                       C:
RAPU-CONT-SW
                         2
                                           03, 19, 21, 25, 56 S:
                                       C:
RAPU-DOOR-OPEN-LT
                                       C:
                                           03, 21, 56
                         3 A03/06
                                           74
RAPU-EGT-IND
                                       S:
                                       C:
RAPU-FIRE-HANDLE
                         1
                                           56
                                      C:
                                           03, 23, 57
RAPU-ISO-SW
RAPU-ISO-VALVE-OPEN-LT
                                       C:
                                           57
RAPU-ON-SPEED-LT
                         1
                                           03, 21
                                                    S: 03, 04, 74
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MONVAR VARIABLE
                        DATA
                               SAR
                                       NAVIGATIONAL PROFILE, CHECKLIST/PROCEDURE,
                        TYPE
                                       PARAMETER REFERENCES
 RAPU-START-LT
                          1
                                       C: 03, 21, 56
 RAT~SW
                          2
                                       C: 04, 12, 24
 RATE-OF-TURN
                                          AL
 RECIRC-FAN-SW
                          1
                                           25, 44, 57
 REFUEL-AUX1-SW
                                       C:
                                          09, 44, 91
 REFUEL-AUX2-SW
                          1
                                           09, 44, 91
 REFUEL-AUX3-SW
                          1
                                           09, 44, 91
                                      C:
 REFUEL-AUX4-SW
                          1
                                      C:
                                           09, 44, 91
 REFUEL-EXRG1-SW
                                      C:
                                          09, 44, 91
 REFUEL-EXRG2-SW
                                      C:
                                          09, 44, 91
 REFUEL-EXRG3-SW
                                          09, 44, 91
 REFUEL-EXRG4-SW
                         1
                                      C:
                                          09, 44, 91
 RELIEF-CREW-SW
                         2 A03/20
                                           57
                                      C:
 ROLL
                         3 SAME
                                          75 P:
                                      S:
                                                   82
                                                        ; AS BANK
 RUDDER-LIMIT-SW
                         1
                                      C:
                                          04, 24
 RUDDER-LIMITER
                         1
                                      C:
                                          12
 RUDDER-PEDAL
                                      C:
                                          24, 61
 RUDDER-TRIM-GROUND-SW
                         1
                                      C:
                                          61
 RUDDER-TRIM-IND
                                      C:
                                          24
 RUDDER-TRIM-POWER-SW
                                      C:
                                          61
 SHORT-DISC-SW
                         1
                                      C:
                                          56
 SKID-CONTROL-SW
                                      C:
                                          04, 22, 60, 68, 94
SKID-CONTROL-TEST-1-SW 1
                                      C:
                                          60
SKID-CONTROL-TEST-2-SW
                         1
                                      C:
                                          60
SKID-CONTROL-TEST-3-SW
                         1
                                      C:
                                          60
SLAT-DRIVE-SW
                         1
                                      C:
                                          12
SLAT-POS-IND
                                      C:
                                          24, 68
STALLIMITER1-OFF-LT
                                      C:
                                          20
STANDBY-COMPASS
                         3 SAME
                                       H
                                                ; AS MAG-HEADING
SYS1-ATM-PUMP-PRESS-LT
                        1
                                      C: 21, 44, 59
SYS1-ATM-PUMP-SW
                         1
                                          19, 21, 44, 59, 63, 92
                                      C:
                                                                   S: 76
SYS1-ATM-START-SW
                                      C:
                                          21, 44, 59
                                                       S: 76
SYS1-ATM-VALVE-OPEN-LT 1
                                      C:
                                          21, 44, 59
SYS1-BOOST-PRES-LOW-LT 1
                                      C:
                                         10, 92
SYS1-BOOST-PUMP-SW
                         1
                                      C:
                                          10, 11, 19, 21, 59, 63
SYS1-BOT-PRES-LOW-LT
                                      C:
SYS1-BOT-SW
                                      C:
                                          19, 21, 25, 44, 92
                                                                   76
SYS1-FLUID-EMPTY
                        1
                                     C:
                                          10
SYS1-HYD-PRESSURE
                        3
                                     C:
                                          21, 25, 92
                                                       S: 76, 77
SYS1-TOP-PRES-LOW-LT
                                     C: 92
SYS1-TOP-SW
                        1
                                         19, 21, 25, 44
                                     C:
SYS2-BOOST-PRES-LOW-LT
                                     C:
                                          10, 92
SYS2-BOT-PRES-LOW-LT
                        1
                                     C:
                                          92
SYS2-BOT-SW
                        1
                                     C:
                                         19, 21, 44, 92
                                                               77
SYS2-HYD-PRESSURE
                                     C: 92
                                             S: 77, 78
SYS2-TOP-PRES-LOW-LT
                        1
                                     C:
                                         92
SYS2-TOP-SW
                                     C:
                                         19, 21, 44
SYS3-BOOST-PRES-LOW-LT
                                     C:
                                         10, 92
SYS3-BOT-PRES-LOW-LT
                        1
                                     C:
                                         92
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                                       19, 21, 44, 92
SYS3-BOT-SW
                        1
                                     C: 92 S: 77, 78
                        3
SYS3-HYD-PRESSURE
                                         92
                                     C:
SYS3-TOP-PRES-LOW-LT
                        1
                                     C: 19, 21, 44
                        1
SYS3-TOP-SW
                                         21, 44, 59
SYS4-ATM-PUMP-PRESS-LT
                                                                  S: 79
                                       19, 21, 44, 59, 63, 92
SYS4-ATM-PUMP-SW
                                         21, 44, 59
                                                      s: 79
                                     C:
SYS4-ATM-START-SW
                                         21, 44, 59
SYS4-ATM-VALVE-OPEN-LT
                                     C:
                                     C: 92
SYS4-BOOST-PRES-LOW-LT
                                     c: 10, 11, 19, 21, 59, 63
SYS4-BOOST-PUMP-SW
                                     C: 10, 92
SYS4-BOT-PRES-LOW-LT
                                     C: 19, 21, 25, 44, 92
SYS4-BOT-SW
                                     C: 10
SYS4-FLUID-EMPTY
                                     C: 21, 25, 92
                                                    S: 78, 79
SYS4-HYD-PRESSURE
                                     C: 92
SYS4-TOP-PRES-LOW-LT
                                                          S: 79
                                         19, 21, 25, 44
                                     C:
SYS4-TOP-SW
                                     P: 80
T/R1-DC-LOAD
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T/R2-DC-LOAD
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                                     D A
TACAN-DME
                        2
                                     DEHA
TACAN1-ANT-SW
                        3
                                     DEHA
TACAN1-CHANNEL
                        4 SAME
                                     D A
                                               : AS TACAN-DME
TACAN1-DME
                                     DEHA
TACAN1 -- FUNC-SW
                                     DEHA
                        1
TACAN1-MODE-SW
                                               ; AS TACAN-DME
                        4 SAME
                                     D A
TACAN2-DME
                                     C: 22, 64, 68, 93, 94 S: 14, 58, 71
                        3 A01/30C
THROTTLE1
                                             C: 22, 64, 68, 93, 94
                        3 A01/29C
                                     D
THROTTLE2
                                             S: 26, 58, 71
                                                                      s: 30
                                             C: 22, 64, 68, 93, 94
                        3 A01/26C
THROTTLE3
                                     D
                                     v: 22, 64, 68, 93, 94 s: 38
THROTTLE4
                        3 A01/25C
                        4 A08/13F
                                     C: 09, 91
TOTAL-FUEL-QTY
                                        57
                        2 A03/24
                                     C:
TROOP-CMPT-SW
                                         04, 12, 63, 68
                                     C:
U-AOA-VANE-HEATFR-SW
                        1
                                     C: 12, 62
                        1
U-RUDDER-SYS1-SW
                                     C: 12, 62
U-RUDDER-SYS3-SW
                        1
                        2
                                     C:
                                        12, 22, 56
UHF1-MODE-SW
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en-ground	1	A15/27	DL (S: 56,	05, 58,	03, (06, 63,	04, 0 14,	30, 3 9, 64 26, 3 65, 6	4, 9: 30, :	l, 94 38, 4	4 47 , !	55,	75
THROTTLE1	3	A01/30C					93,	94	s:	14,	58,	71
PARAMET	ER	15			1	P.15						
ENG1-FUEL-FLOW		A03/22C	S:									
ENG1-START-BUTTON ENG1-TIT	1	A04/29C		93 94		15,	21					
ENG INE-1-RUNNING	1	1047 250	C:		91		03,	09,	14,	15,	17,	18
PARAMET	ER	16			1	2.16						
ENG1-N1-RPM ENGINE-1-RUNNING	3	A04/14C				s:	03,	09,	14,	15,	17,	18
PARAMET	ER	17			1	2.17						
ENG1-N2-RPM ENGINE-1-RUNNING	3	A04/09C	C: C: P:	92, 10, 16,	91	s: s:	04, 03,			76 15,	17,	18
PARAMET	ER	18			1	2.18						
ENG1-N2-RPM ENG1-OIL-PRESSURE ENG1-OIL-TEMP	3	A04/09C A03/07C A19/04	C: S:	92, 18 18,		s:	04,	17,	18,	76		
eng in e-1-running	1		C: P:	10, 16,		s:	03,	09,	14,	15,	17,	18

PARAME TE	R 19		3	P.19					
ENG1-FUEL-&-START-IGN CONTROL ENG1-OIL-TEMP	2 3 A19/04		12, 45, 18, 19	93	s:	19	P:	20	
PARAME TEI	20		1	P.20					
ENG1-FUEL-&-START-IGN			12, 45,	93	s:	19	P:	20	
ENGI-START-CYCLE ENGINE-1-RUNNING		C:	20 10, 91 16, 20	s:	03,	09,	14,	15,	17, 18
PALAME TER	21		I	2.21					
ENG1-TIT 3	A04/29C	C:	94 S:	15,	21				
PARAMETER	. 22		I	2.22					
	A03/18C								
ENG2-START-BUTTON 1 ENG2-TIT 3			93 S:		00				
ENGINE-2-RUNNING 1	A04/25C	C:	94 S: 10 S: 27, 28		10,	22,	23,	24,	26
PARAME TER	. 23		P	.23					
ENG2-N2-RPM 3 ENGINE-2-RUNNING 1	A04/02C	C:	92, 93 10 S: 27, 28						26
DAD A MOREO	24		·						
PARAMETER	24		P	.24					
	A04/02C A03/03C		92, 93	s:	04,	23,	24,	77	
	A03/03C A20/04	S: S:	24 24, 25						
ENGINE-2-RUNNING 1	• "	C: P:	10 S: 27, 28	03,	10,	22,	23,	24,	26

P.25

ENG2-FUEL-&-START-IGN			12, 45, 93	s:	25	P:	28
ENG2-OIL-TEMP	3 A20/04	S:	24, 25				

PARAMETER 26

P.26

ENG2-P-EPR	4 A2C/3OC	C: 94 S: 26
ENGINE-2-RUNNING	1	C: 10 S: 03, 10, 22, 23, 24, 26
		P: 27, 28
FLAP-POS-IND	3 A18/29CF	C: 14, 22, 24, 26, 60, 68, 94
		S: 05, 14, 26, 30, 38, 47 P: 82
ON-GR OUND	1 A15/27	DL C: 03, 04, 09, 64, 91, 94
		S: 05, 06, 14, 26, 30, 38, 47, 55,
		56, 58, 63, 64, 65, 66, 68, 69, 74, 75
		P: 52, 82, 83, 84
THROTTLE2	3 A01/29C	D C: 22, 64, 68, 93, 94
		S: 26, 58, 71

PARAMETER 27

P.27

ENG2-P-N1-RPM	3 A04/13C	P:	27							
ENGINE-2-RUNNING	1		10 27,	S: 28	03,	10,	22,	23,	24,	26

PARAMETER 28

P.28

ENG2-FUEL-&-START-IGN	2	C:	12,	45,	93	s:	25	P:	28	
ENG 2-START-CYCLE	1	P:	28							
ENGINE-2-RUNNING	1	C:	10	S:	03,	10,	22,	23,	24,	26
		P:	27.	28						

PARAMETER 29

P.29

ENG2-TIT 3 A04/25C C: 94 S: 22, 29

PARAME	TER 30	P.30
ENG3-E PR ENG INE-3-RUNNING	4 A21/30C	C: 94 S: 30 C: 10 S: 03, 11, 30, 31, 33, 35 P: 32, 36
FIAP-POS-IND	3 A18/29CF	
ON-GROUND	1 A15/27	DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
THROTTLE3	3 A01/26C	
PARAME	TER 31	P.31
I MARIAN	J	
eng3-fuel-flow	3 A03/26C	
ENG3-START-BUTTON	1	C: 93 S: 31
ENG3-TIT	3 A04/26C	
ENG INE -3-RUNNING	1	C: 10 S: 03, 11, 30, 31, 33, 35 P: 32, 36
PARAME	TER 32	P.32
ENG3-N1-RPM	3 404/010	P: 32
ENGINE-3-RUNNING	1	C: 10 S: 03, 11, 30, 31, 33, 35
		P: 32, 36
PARAME	TER 33	P.33
ENG3-F-N2-RPM	3 A04/06C	c: 92 s: 04, 33
ENG3-01L-PRESSURE	3 A03/05C	S: 33
ENG3-01L-TEMP	3 A21/04	S: 33, 34
ENGINE-3-RUNNING	1	C: 10 S: 03, 11, 30, 31, 33, 35
		P: 32, 36
PARAME	TER 34	P.34

2 3 A21/04

ENG3-FUEL-&-START-IGN ENG3-OIL-TEMP

C: 12, 45, 93 S: 34 S: 33, 34

P: 36

PARAMETER	3	5
T TITUTITIES Y TITL	J	_

P.35

PARAMETER 36

P.36

ENG3-FUEL-&-START-IGN	2	C:	12,	45,	93	S:	34	P:	36	
ENG3-START-CYCLE	1	P:	36	·						
ENGINE-3-RUNNING	1	C:	10	s:	03,	11,	30,	31,	33,	35
		_	32.		•	•	•	•	•	

PARAMETER 37

P.37

ENG3-TIT 3 A04/26C C: 94 S: 31, 37

PARAMETER 38

P.38

ENG4-EPR	4 A22/30C	C: 94 S: 38
ENG INE-4-RUNNING	1	C: 10 S: 03, 12, 38, 39, 41, 43 P: 42, 45
FLAP-POS-IND	3 A18/29CF	C: 14, 22, 24, 26, 60, 68, 94 S: 05, 14, 26, 30, 38, 47 P: 82
ON-GROUND	1 A15/27	DL C: 03,04,09,64,91,94 S: 05,06,14,26,30,38,47,55, 56,58,63,64,65,66,68,69,74,75 P: 52,82,83,84
THROTTLE4	3 A01/25C	C: 22, 64, 68, 93, 94 S: 38

PARAMETER 39

P.39

ENG4-F-N2-RPM	3 A04/05C	C:	92	s:	04,	39				
ENG4-OIL-PRESSURE	3 A03/01C	s:	39		-					
ENG4-01L-TEMP	3 A22/04	s:	39,	40						
ENGINE-4-RUNNING	1	C:	10	S:	03	, 12,	38,	39,	41,	43
		P:	42,	45		. •		·	•	

PARAMETER 40

P.40

ENG4-FUEL-&-START-IGN 2 C: 12, 45, 93 S: 40 P: 45 ENG4-OIL-TEMP 3 A22/04 S: 39, 40

PARAMETEI	R 41	P.41
PARAME TER	42	P•42
ENG4-P-N1-RPM 3 ENGINE-4-RUNNING 1	A04/10C	P: 42 C: 10 S: 03, 12, 38, 39, 41, 43 P: 42, 45
PARAME TER	. 43	P•43
ENG4-P-N2-RPM 3 ENGINE-4-RUNNING 1	A04/05C	C: 93 S: 43, 79 C: 10 S: 03, 12, 38, 39, 41, 43 P: 42, 45
PARAME TER	44	P.44
ENG4-P-TIT 3	A04/30C	C: 94 S: 41, 44
PARAMETER	45	P•45
ENG4-FUEL-&-START-IGN 2		C+ 12 45 02 0. (0 = 45
ENG4-START-CYCLE 1		C: 12, 45, 93 S: 40 P: 45 P: 45
ENGINE-4-RUNNING 1		C: 10 S: 03, 12, 38, 39, 41, 43 P: 42, 45
PARAMETER	46	P.46
APU/EXT-POWER-SW 2		C: 03, 12, 19, 21, 56, 92 S: 04
EXT-ELECTRIC-POWER 1		P: 46
EXT-POWER-LOADMETER 4		C: 19, 21, 56 P: 46 P: 46

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PARAMETER 47
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                                          14, 64 S: 05, 47, 57, 69, 75
AIRSPEED
                         3
                                          09, 64, 91, 94
ALTITUDE-AGL
                                      S: 05, 07, 08, 47, 71, 75
C: 14, 22, 24, 26, 60, 68, 94
S: 05, 14, 26, 30, 38, 47 P: 82
                         3 A18/29CF
FLAP-POS-IND
                                      DL C: 03, 04, 09, 64, 91, 94
ON-GROUND
                         1 A15/27
                                          05, 06, 14, 26, 30, 38, 47, 55,
                                      s:
                                       56, 58, 63, 64, 65, 66, 68, 69, 74, 75
                                       P: 52, 82, 83, 84
                                       s: 05, 47, 57, 71
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VERTICAL-SPEED
                PARAMETER 48
                                                  P.48
                                      P: 48
GEN1-LOADMETER
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GEN1-SW
                PARAMETER 49
                                                  P.49
GEN2-LOADMETER
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                                      C:
                                          92
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GEN2-OUT-LT
                PARAMETER 50
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GEN3-LOADMETER
                                      P:
                                          50
                                       C: 03, 12 S: 03, 04
                                                                  P: 50
GEN3-SW
                                                  P.51
                PARAMETER 51
                                          51
GEN4-LOADMETER
                                      P:
                                       C: 03, 12 S: 03, 04
                                                                   P: 51
GEN4-SW
                                                  P.52
                PARAMETER 52
GROUND-SPEED
                         3 INS?
                                       s: 63, 64, 65, 66, 68 P: 52
                                       DL C: 03, 04, 09, 64, 91, 94
ON-GROUND
                         1 A15/27
                                       s: 05, 06, 14, 26, 30, 38, 47, 55,
                                       56, 58, 63, 64, 65, 66, 68, 69, 74, 75
                                       P: 52, 82, 83, 84
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PARAMETER 53 P.53 L-LANDING-LIGHT-SW 1 C: 09, 11, 60, 68, 91 PARAMETER 54 P.54 ENG1-BLEED-AIR-SW 1 A04/16 C: 57, 92 S: ENG2-BLEED-AIR-SW 1 A04/17 C: 57, 92 S: 54 L-DUCT-OVERHEAT-LT 1 S: 54 L-MANIFOLD-PRESSURE 3 A07/17,25 S: 54 LAPU-BLEED-AIR-SW C: 03, 19, 21, 56, 57, 92 S: 54, 73 PARAMETER 55 P.55 LANDING-GEAR-LEVER 1 A01/03 C: 10, 11, 12, 13, 14, 94 S: 55 P: 59, 60, 61, 62, 67 ON-GROUND 1 A15/27 DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84 PARAMETER 56 P.56 LAPU-CONT-SW C: 03, 19, 21, 25, 56 S: 56 LAPU-EGT-IND 3 A03/02 S: 56

LAPU-CONT-SW 2 C: 03, 19, 21, 25, 56 S: 56
LAPU-EGT-IND 3 A03/02 S: 56
LAPU-ON-SPEED-LT 1 C: 03, 21 S: 03, 04, 56
ON-GROUND 1 A15/27 DL C: 03, 04, 09, 64, 91, 94
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PARAMETER 57 P.57

AIRSPEED C: 14, 64 S: 05, 47, 57, 69, 75 ALTITUDE 4 A06/30F S: 01, 02, 05, 57 DEHAL MACH 4 A05/30F S: 05, 57 NLG-IND 2 S: 05, 57 P: 67 VERTICAL~SPEED 3 S: 05, 47, 57, 71 P: 83

PARAME	TER 58	P.58
MAG-HEADING ON-GROUND	3 1 A15/27	EHAL S: 58 DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
THROTTLE1 THROTTLE2	3 A01/30C 3 A01/29C	C: 22, 64, 68, 93, 94 S: 14, 58, 71 D C: 22, 64, 68, 93, 94 S: 26, 58, 71
PARAME	TER 59	P.59
LANDING-GEAR-LEVER MLG-EMER-EXT-L-A MLG-IND-L-A	1 A01/03 1 2	C: 10, 11, 12, 13, 14, 94 S: 55 P: 59, 60, 61, 62, 67 P: 59 S: 05 P: 59
PARAME	TER 60	P.60
LANDING-GEAR-LEVER MLG-EMER-EXT-L-F MLG-IND-L-F	1 A01/03 1 2	C: 10, 11, 12, 13, 14, 94 S: 55 P: 59, 60, 61, 62, 67 P: 60 P: 60
PARAME	TER 61	P.61
LANDING-GEAR-LEVER MLG-EMER-EXT-R-A MLG-IND-R-A	1 A01/03 1 2	C: 10, 11, 12, 13, 14, 94 S: 55 P: 59, 60, 61, 62, 67 P: 61 P: 61
PARAME	TER 62	P.62
LANDING-GEAR-LEVER MLG-EMER-EXT-R-F MLG-IND-R-F	1 A01/03 1 2	C: 10, 11, 12, 13, 14, 94 S: 55 P: 59, 60, 61, 62, 67 P: 62 P: 62

	PARAMETER	63	P.63
GROUND-SPEED MLG-POS-IND-L-A ON-GROUND	4	INS? A15/27	S: 63, 64, 65, 66, 68 P: 52 C: 68 S: 63 DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
	Parameter	64	P.64
GROUND-SPEED MLG-POS-IND-L-F ON-GROUND	4	INS? A15/27	S: 63, 64, 65, 66, 68 P: 52 C: 68 S: 64 DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
	PARAMETER	65	P.65
GROUND-SPEED MLG-POS-IND-R-A ON-GROUND	4	INS? A15/27	S: 63, 64, 65, 66, 68 P: 52 C: 68 S: 65 DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84

P.66

GROUND-SPEED	3 INS?	S: 63, 64, 65, 66, 68 P: 52
MLG-POS-IND-R-F	4	C: 68 S: 66
on-ground	1 A15/27	DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84

PARAMETER 67

P.67

LANDING-GEAR-LEVER	1 A01/03	C: 10, 11, 12, 13, 14, 94 S: 55
		P; 59, 60, 61, 62, 67
NLG-EMER-EXT-SW	1	P: 67
NLG-IND	2	S: 05, 57 P: 67

R-LANDING-LIGHT-SW 1

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NLG-POS-XWIND-IND	3 INS? 4 1 A15/27	S: 63, 64, 65, 66, 68 P: 52 C: 68 S: 68 DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
PARAME TEN	R 69	P.69
AIRSPEED	3	C: 14, 64 S: 05, 47, 57, 69, 75
	4	8: 69
	L A15/27	DL C: 03, 04, 09, 64, 91, 94
		S: 05, 06, 14, 26, 30, 38, 47, 55,
		56, 58, 63, 64, 65, 66, 68, 69, 74, 75
		P: 52, 82, 83, 84
PARAMETER NOSE-LANDING-LIGHT-SW	_	P.70 C: 11, 60, 68 P: 70
PARAMETE	R 71	P.71
ALTITUDE-AGL	2	C: 09, 64, 91, 94
ALITIUDE-AGL	,	S: 05, 07, 08, 47, 71, 75
PITCH	3 FDC	S: 71
	3 A01/30C	C: 22, 64, 68, 93, 94 S: 14, 58, 71
	3 A01/30C	D C: 22, 64, 68, 93, 94
THROTTLE2	. WAT 1 TAC	S: 26, 58, 71
UPDTICAL COPPD 2	3	S: 20, 30, 71 S: 05, 47, 57, 71 P: 83
VERTICAL-SPEED 3	,	3. U3, 41, 31, 11 E. U3
PARAMETE	R 72	P.72

C: 09, 11, 60, 68, 91 P: 72

P.73 PARAMETER 73 ENG3-BLEED-AIR-SW 1 A04/18C: 57, 92 S: 57, 92 ENG4-BLEED-AIR-SW 1 A04/19 C: S: 73 03, 19, 21, 56, 57, 92 S: 54, 73 1 C: LAPU-BLEED-AIR-SW R-DUCT-OVERHEAT-LT S: 73 3 A07/10,14 S: 73 R-MANIFOLD-PRESSURE PARAMETER 74 P.74 ON-GROUND 1 A15/27 DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84 C: 03, 19, 21, 25, 56 S: 74 RAPU-CONT-SW 3 A03/06 RAPU-EGT-IND S: 74 03, 21 RAPU-ON-SPEED-LT S: 03, 04, 74 P.75 PARAMETER 75 AIRSPEED 14, 64 S: 05, 47, 57, 69, 75 09, 64, 91, 94 ALTITUDE-AGL 05, 07, 08, 47, 71, 75 DL C: 03, 04, 09, 64, 91, 94 ON-GROUND 1 A15/27 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84 S: 75 ROLL 3 SAME P: 82 ; AS BANK PARAMETER 76 P.76 3 A04/09C ENG1-N2-RPM C: 92, 93 S: 04, 17, 18, 76 SYS1-ATM-PUMP-SW 19, 21, 44, 59, 63, 92 76 C: 21, 44, 59 SYS1-ATM-START-SW S: 76 19, 21, 25, 44, 92 S: SYS1-BOT-SW 1 C: 21, 25, 92 S: 76, 77 SYS1-HYD-PRESSURE C:

19, 21, 25, 44

S: 76

SYS1-TOP-SW

P.77 PARAMETER 77 ENG2-N2-RPM 3 A04/02C C: 92, 93 S: 04, 23, 24, 77 10, 11, 25, 44, 59, 63, 92 S: 77 PTU-1/2-SW C: 1 S: 77, 78 PTU-2/3-SW 44, 59, 63, 92 21, 25, 92 S: 76, 77 SYS1-HYD-PRESSURE 3 C: 13, 21, 44, 92 SYS2-BOT-SW 1 C: S: 77 3 C: 92 S: 77, 78 SYS2-HYD-PRESSURE 19, 21, 44 S: C: 77 SYS2-TOP-SW 92 S: 77, 78 SYS3-HYD-PRESSURE C: PARAMETER 78 P.78 ENG3-P-N2-RPM 3 A04/06C C: 93 S: 35, 78 44, 59, 63, 92 S: 77, 78 10, 11, 25, 44, 59, 63 S: 78 PTU-2/3-SW PTU-3/4-SW C: 92 S: 77, 78 SYS2-HYD-PRESSURE 3 19, 21, 44, 92 SYS3-BOT-SW 1 C: 92 S: 77, 78 19, 21, 44 S: SYS3-HYD-PRESSURE C: 78 C: SYS3-TOP-SW 1 SYS4-HYD-PRESSURE 21, 25, 92 S: 78, 79 PARAMETER 79 P.79 3 A04/05C C: 93 s: 43, 79 ENG4-P-N2-RPM 19, 21, 44, 59, 63, 92 79 SYS4-ATM-PUMP-SW 1 21, 44, 59 8: 79 1 C: SYS4-ATM-START-SW 19, 21, 25, 44, 92 SYS4-BOT-SW 1 C: 21, 25, 92 S: 78, 79 SYS4-HYD-PRESSURE 3 19, 21, 25, 44 SYS4-TOP-SW PARAMETER 80 P.80 C: 03, 12 P: 80 GEN1-BUS-TIE-SW T/R1-DC-LOAD P: 80

いいかは、関係ないののののではなってあるとのを関していいからいの間ではないないを見る事情であるとのなるとのであるとうなるとのできましてものできますとしていることできま

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P:

PARAMETER 81

GEN4-BUS-TIE-SW

T/R2-DC-LOAD

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P.82

FLAP-POS-IND	3 A18/29CF	C: 14, 22, 24, 26, 60, 68, 94 S: 05, 14, 26, 30, 38, 47 P: 82
ON-GROUND	1 A15/27	DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
ROLL VERT-ACCELEROMETER	3 SAME 4 A05/21F	S: 75 P: 82 ; AS BANK P: 82
PARAME	TER 83	P.83
on-ground	1 A15/27	DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
VERTICAL-SPEED	3	s: 05, 47, 57, 71 P: 83
PARAME	TER 84	P.84
on-ground	1 A15/27	DL C: 03, 04, 09, 64, 91, 94 S: 05, 06, 14, 26, 30, 38, 47, 55, 56, 58, 63, 64, 65, 66, 68, 69, 74, 75 P: 52, 82, 83, 84
WAY	4	P: 84

APPENDIX H

SIGNALS REQUIRED FOR NAVIGATIONAL PROFILES

SOURCE OF VARIABLES REQUIRED FOR NAVIGATIONAL PROFILE RELATED MONITORING

NAVIGATIONAL PROFILES

IMPOR- TANCE*	VARIABLE	TYPE	SOURCE
1	THROTTLE2	3	MADARS A01/29C
1	THROTTLE3	3	MADARS A01/26C
2	ADF1-FREQUENCY	3	
2	ADF1-FUNC-SW	2	
2	ADF2-FREQUENCY	3	
2	ADF2-FUNC-SW	2	
2	MAG-HEADING	3	
2	TACAN1-ANT-SW	2	
2	TACAN1-CHANNEL	3	
2	TACAN1-FUNC-SW	2	
2	TACAN1-MODE-SW	1	
2	VOR1-FREQUENCY	4	
2	VOR1-SW	1	
2	VOR2-FREQUENCY	4	
2	VOR2-SW	1	
3 3	BANK	3	INS
	C-NAV-SELECT	2	FDC2
3	C-RATE-OF-TURN		SAME AS RATE-OF-TURN
3 3 3	INS1/3-ROLL	3	SAME AS BANK
3	INS2/3-ROLL	3	SAME AS BANK
	P-NAV-SELECT	2	FDC1
3	P-RATE-OF-TURN	4	SAME AS RATE-OF-TURN
3	RATE-OF-TURN	4	
4	ON-GROUND	1	MADARS A15/27
5	C-ROLL-HUB-FORCE	3	
5	P-ROLL-HUB-FORCE	3 3 3	
5	PITCH-C-HUB-FORCE	3	
	PITCH-P-HUB-FORCE	3	
6	C-COURSE-SET	3	
6	COURSE-SET	3	COMPUTED BASED ON WHO IS FLYING
6	P-COURSE-SET	3	
6	TACAN-DME	4	FDC1
6	TACAN1-DME	4	
6	TACAN2-DME	4	???
7	ALTITUDE	4	MADARS A06/30F
7	C-ALTITUDE	4	SAME AS ALTITUDE

7	C-CDI-WARNING	1	FDC2
7	C-G/S-DEVIATION-WARN	1	FDC2
7	CDI-WARNING	1	COMPUTED BASED ON WHO IS FLYING
7	GSI-WARNING	1	COMPUTED BASED ON WHO IS FLYING
7	P-ALTITUDE	4	SAME AS ALTITUDE
7	P-CDI-WARNING	1	FDC1
7	P-G/S-DEVIATION-WARN	1	FDC1
9	C-CDI	4	FDC2
9	C-G/S-DEVIATION-IND	4	FDC2
9	CDI	4	COMPUTED BASED ON WHO IS FLYING
9	GSI	4	COMPUTED BASED ON WHO IS FLYING
9	LATITUDE	5	INS
9	LONG ITUDE	5	INS
9	P-CDI	4	FDC1
9	P-G/S-DEVIATION-IND	4	FDC2

MONITORABLE PARAMETERS

IMPOR- TANCE*	VARIABLE	TYPE	SOURCE
2	ANGLE-OF-ATTACK	3	
3	L-LANDING-LIGHT-SW	1	
3	NOSE-LANDING-LIGHT-SW	1	
3	R-LANDING-LIGHT-SW	1	
3	VERTICAL-SPEED	3	
4	GROUND-SPEED	3	
4	ON-GROUND	1	MADARS A15/27
5	NLG-STEER ING-IND	4	
6	PITCH	3	FDC
6	ROLL	3	SAME AS BANK
6	YAW	4	
7	ALTITUDE	4	MADARS A06/30F
8	AIRSPEED	3	
8	ALTITUDE-AGL	3	
8	FLAP-HANDI.E	3	
8	FLAP-POS-IND	3	MADARS A18/29CF
8	LANDING-GEAR-LEVER	1	MADARS A01/03
8	NLG-IND	2	

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^{*} IMPORTANCE RANGES 0..9, LEAST..MOST

APPENDIX I

SYSTEM DEVELOPMENT COSTS

The following cost estimates are provided based on the design of an Airborne Performance Measurement System as presented in Part IV of the final report. The cost estimates are a function of 1983 rates and will vary with the implementation schedule.

Labor	\$295,000
Material	106,000
Travel	26,000
Computer Time	8,200
Documentation	100
Total Development Cost	\$435,300

The labor estimate includes engineering time to design, manufacture and implement the system. This includes both hardware and software engineering, plus the time required to produce system documentation.

The material estimate includes all hardware components, both off-the-shelf items as well as newly designed equipment. Also included are costs for a microcomputer development system and material items to support the development effort.

The travel costs include trips for existing system research and installation and checkout. The computer time cost is for software development at the contractor's facility.